FOR PARTS CONTACT
RATELCO
624-7770
615 YALE N.
BEN OHASHI
PARTS MANAGER
DATA PRODUCTS

## MODEL <br> M3000-100,200, 300,400 * <br> M4000-100, 200 *

* AVAILABLE OPTION:

StepScan

Model M3000 (12"-CRT)


Model M4000 (15"-CRT)

## CAUTION

NO WORK SHOULD BE ATTEMPTED ON ANY EXPOSED MONITOR CHASSIS BY. ANYONE NOT FAMILIAR WITH SERVICING PROCEDURES AND PRECAUTIONS.

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CAUTION: NO WORK SHOULD BE ATTEMPTED ON AN EXPOSED MONITOR CHASSIS BY ANYONE NOT FAMILIAR WITH SERVICING PROCEDURES AND PRECAUTIONS.

1. SAFETY PROCEDURES should be developed by habit so that when the technician is rushed with repair work, he automatically takes precautions.
2. A GOOD PRACTICE, when working on any unit, is to first ground the chassis and to use only one hand when testing circuitry. This will avoid the possibility of carelessly putting one hand on chassis or ground and the other on an electrical connection which could cause a severe electrical shock.
3. Extreme care should be used in HANDLING THE PICTURE TUBE as rough handling may cause it to implode due to atmospheric pressure ( 14.7 lbs . per sq. in.). Do not nick or scratch glass or subject it to any undue pressure in removal or installation. When handling, safety goggles and heavy gloves should be worn for protection. Discharge picture tube by shorting the anode connection to chassis ground (not cabinet or other mounting parts). When discharging, go from ground to anode or use a well insulated piece of wire. When servicing or repairing the monitor, if the cathode ray tube is replaced by a type of tube other than that specified under the Motorola Part Number as original equipment in this Service Manual, then avoid prolonged exposure at close range to unshielded areas of the cathode ray tube. Possible danger of personal injury from unnecessary exposure to X-ray radiation may result.
4. An ISOLATION TRANSFORMER should always be used during the servicing of a unit whose chassis is connected to one side of the power line. Use a transformer of adequate power rating as this protects the serviceman from accidents resulting in personal injury from electrical shocks. It will also protect the chassis and its components from being damaged by accidental shorts of the circuitry that may be inadvertently introduced during the service operation.
5. Always REPLACE PROTECTIVE DEVICES, such as fishpaper, isolation resistors and capacitors and shields after working on the unit.
6. If the HIGH VOLTAGE is adjustable, it should always be ADJUSTED to the level recommended by the manufacturer. If the voltage is increased above the normal setting, exposure to unnecessary $X$-ray radiation could result. High voltage can accurately be measured with a high voltage meter connected from the anode lead to chassis.
7. BEFORE RETURNING A SERVICED UNIT, the service technician must thoroughly test the unit to be certain that it is completely safe to oderate without danger of electrical shock. DO NOT USE A LINE ISOLATION TRANSFORMER WHEN MAKING THIS TEST.

In addition to practicing the basic and fundamental electrical safety rules, the following test, which is related to the minimum safety requirements of the Underwriters Laboratories should be performed by the service technician before any unit which has been serviced is returned.


Voltmeter Hook-up for Safety Check

A 1000 ohm per volt AC voltmeter is prepared by shunting it with a 1500 ohm, 10 watt resistor. The safety test is made by contacting one meter probe to any portion of the unit exposed to the operator such as the cabinet trim, hardware, controls, knobs, etc., while the other probe is held in contact with a good "earth" ground such as a cold water pipe.

The $A C$ voltage indicated by the meter may not exceed $7 \frac{1}{2}$ volts. A reading exceeding $71 / 2$ volts indicates that a potentially dangerous leakage path exists between the exposed portion of the unit and "earth" ground. Such a unit represents a potentially serious shock hazard to the operator.

The above test should be repeated with the power plug reversed, when applicable.

NEVER RETURN A MONITOR which does not pass the safety test until the fault has been located and corrected.

ELECTRICAL SPECIFICATIONS *

|  | MODEL M3000 | MODEL M4000 |
| :---: | :---: | :---: |
| PICTURE TUBE: | $12^{\prime \prime}$ measured diagonally ( 305 mm ); 74 sq. in. viewing area ( $477 \mathrm{sq} . \mathrm{cm}$ ); $110^{\circ}$ deflection angle; integral implosion protection; P4 phosphor standard | $15^{\prime \prime}$ measured diagonally ( 381 mm ); 100 sq. in. viewing area ( $645 \mathrm{sq} . \mathrm{cm}$ ); $110^{\circ}$ deflection angle; integral implosion protection; P4 phosphor standard |
| POWER INPUT: | 115/230V AC, 60 watts (nominal), or 70 V DC |  |
| FUSES: | 0.8 Amp Slo Blo | 0.8 Amp Slo-Blo |
| LOW VOLTAGE POWER SUPPLY: | Electronically regulated over AC inputs from 107 V to 135 V , or 214 V to 270 V |  |
| INPUT SIGNALS: | COMPOSITE VIDEO INPUT: 0.5 V to 2.5 V composite $\mathrm{P}-\mathrm{P}$, sync negative (input im- <br> pedance: 75 ohms terminated, 12 K ohms unterminated), <br> or <br> TTL SEPARATE 2.5 V to 5.0 V P-P, video drive, sync positive at input (in- <br> HORIZONTAL, VERTICAL,  <br> VIDEO: impedance: 75 ohms to 250 ohms video termination,  <br>  $>2 \mathrm{~K}$ ohms vertical and horizontal) |  |
| PULSE RISE TIME (TYPICAL): | 30 V rise in less than 20 nSec |  |
| RESOLUTION (TYPICAL): | 800 lines center, 600 lines corners |  |
| VIDEO RESPONSE (TYPICAL): | Within $-3 \mathrm{~dB}, 10 \mathrm{~Hz}$ to 22 MHz |  |
| LINEARITY: | Within $2 \%$ as measured with standard EIA ball chart and dot pattern |  |
| HIGH VOLTAGE: | 14 kV nominal at 20 uAmp beam current | 17 kV nominal at 20 uAmp beam current |
| HORIZONTAL RETRACE TIME: | 11.0 uSec maximum at 15.75 kHz |  |
| SCANNING FREQUENCY: | Horizontal: $15,750 \mathrm{~Hz} \pm 500 \mathrm{~Hz}$; Vertical: $50 / 60 \mathrm{~Hz}$ |  |
| ENVIRONMENT: | Operating temperature: $0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ <br> Storage temperature: $-40^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ <br> Operating altitude: 10,000 feet maximum ( 3048 meters) <br> Designed to comply with applicable DHEW rules on X-Radiation <br> Designed to enable listing under UL Specification 478 |  |
| TYPICAL DIMENSIONS: | $\begin{aligned} & 9.12^{\prime \prime} \mathrm{H}, 11.40^{\prime \prime} \mathrm{W}, 8.84^{\prime \prime} \mathrm{D} \quad(232 \times \\ & 290 \times 225 \mathrm{~mm}) \end{aligned}$ | $\begin{aligned} & 10.94^{\prime \prime} \mathrm{H}, 12.84^{\prime \prime} \mathrm{W}, 10.22^{\prime \prime} \mathrm{D}(278 \times \\ & 326 \times 260 \mathrm{~mm}) \end{aligned}$ |

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## GENERAL INFORMATION

The monitors described herein are fully transistorized (except CRT) and applicable for displaying alphanumeric characters. The M3000 series monitors use a 12 -inch CRT id the $M 4000$ series monitors use a 15 -inch CRT. All M3000/4000 series monitors are capable of accepting a composite video signal or a non-composite video signal with separate TTL horizontal and vertical sync pulses. (See Schematic diagram.)

The CRT's employed are of the magnetic deflection type with integral implosion protection. An operating voltage of +70 volts DC is required from the regulated power supply for both models. A universal power transformer permits operating the monitor from either 115 or 230 volts AC, $50 / 60 \mathrm{~Hz}$.

Input and output connections for the monitor are made through a 10 -pin edge or header connector on the vertical/ video circuit card. Inputs consist of video, horizontal/ vertical sync, and signal ground. One additional input, an optional TTL level StepScan, may also be connected to the monitor via the 10 -pin edge connector. Output connections are provided for an optional remote brightness control.

Circuitry consists of two stages for video amplification, five stages for vertical sync and deflection processing, five stages for horizontal sync and deflection processing, and a regulated +70 volt power supply. Both models also have available as options, dynamic focusing, vertical blanking nplifier, horizontal sync delay, and StepScan amplifier. (See Schematic diagram.)

Four etched circuit cards are utilized, containing the vertical/video circuit, horizontal circuit, differential amplifier/sync separator circuit and power supply circuit. An optional low voltage logic power supply is available when a remote power source is required for logic interface circuitry. Components are mounted on the top of the circuit cards and plating copper foil on the bottom. Schematic reference numbers are printed on the top and bottom of each circuit card to aid in the location and identification of components for servicing. All standard operating/ adjustment controls are mounted in a convenient manner on the three circuit cards. Refer to Motorola Service Manual VP20, Part No. 68P25253A40 for complete service information on the low voltage logic power supplies and VP21, Part No. 68P25253A41 for complete service information for the composite video circuit card.

## SERVICE NOTES

## CIRCUIT TRACING

Component reference numbers are printed on the top and bottom of the three circuit cards to facilitate circuit rracing. In addition, control names and circuit card termin-
numbers are also shown and referenced on the schematic diagram in this manual.

Transistor elements are identified as follows:
E-emitter, B-base, and C-collector.

## COMPONENT REMOVAL

Removing components from an etched circuit card is facilitated by the fact that the circuitry (copper foil) appears on one side of the circuit card only and the component leads are inserted straight through the holes and are not bent or crimped.

It is recommended that a solder extracting gun be used to aid in component removal. An iron with a temperature controlled heating element would be desirable since it would reduce the possibility of damaging the circuit card foil due to over-heating.

The nozzle of the solder extracting gun is inserted directly over the component lead and when sufficiently heated, the solder is drawn away leaving the lead free from the copper foil. This method is particularly suitable in removing multiterminal components.

When replacing "plug-in" transistors, please observe the following precautions:

1. The transistor sockets are not "captive", which means that the transistor mounting screws also secure the socket. When installing the transistor, the socket must be held in its proper position.
2. When replacing a plug-in transistor, silicone grease (Motorola Part No. 11M490487) should be applied evenly to the top of the heat sink and bottom of the transistor. In addition, be sure a mica insulator is positioned properly between the transistor and heat sink.
3. The transistor mounting screws must be tight before applying power to the monitor. This insures proper cooling and electrical connections. NON-COMPLIANCE WITH THESE INSTRUCTIONS CAN RESULT IN FAILURE OF THE TRANSISTOR AND/OR ITS RELATED COMPO. NENTS.

## NOTE

Use caution when tightening transistor mounting screws. If the screw threads are stripped by excessive pressure, a poor electrical and mechanical connection will result.

## CRT REPLACEMENT

Use extreme care in handling the CRT as rough handling may' cause it to implode due to high vacuum pressure. Do not nick or scratch glass or subject it to any undue pressure in removal or installation. Use goggles and heavy gloves for protection. In addition, be sure to disconnect the monitor from all external voltage sources.

1. Disenarge CRT by shorting 2 nd anode to ground; then remove the CRT socket, deflection yoke and 2 nd anode lead.
2. Remove CRT from the front of the chassis by loosening and removing four screws; one in each corner of the CRT.

## REGULATOR ADJUSTMENT

## NOTE

Misadjustment of the low voltage regulator, or the horizontal oscillator may result in damage to the horizontal output transistor or pulse limiter diode. The following procedure is recommended to insure reliable operation.

1. Connect the monitor to an AC line supply; then adjust supply to 120 volts ( 240 volts in some applications).
2. Apply test signal to proper input. Signal should be of same amplitude and sync rate as when monitor is in service.
3. Adjust HOR. SET coil L50 (on the horizontal circuit card) until display is stable.
4. Connect a DC digital voltmeter or equivalent precision voltmeter to the emitter of the regulator output transistor, Q150 (or any +70 volt test point on the power supply circuit card).
5. Adjust the 70V ADJUST. control, R158, on the power supply circuit card for an output of +70 volts. DO NOT rotate the control through its entire range; damage to the monitor may result.
6. When adjustment is complete, the AC line supply can oe varied between 105 and 130 volts AC to check for oroper regulator operation. With the regulator operating properly, changes in display size should be negligible.

## HORIZONTAL HOLD/OSCILLATOR ADJUSTMENT

Adjust the core of HOR. SET coil L50 until the horizontal blanking lines are vertical, or the CRT display is stable (synced).

## DYNAMIC FOCUS ADJUSTMENT

The DYNAMIC FOCUS coil is factory set and should not normally require further adjustment. However, if it becomes necessary, use Procedure No. 1 for touching up the overall focus. Procedure No. 2 is provided if the CRT (V1) and/or DYNAMIC FOCUS coil (L52) is replaced in the field.

## PROCEDURENO. 1

1. Adjust FOCUS control R70 (on horizontal circuit card) for best focus in the center of the CRT.
2. Adjust DYNAMIC FOCUS coil $L 52$ for best edge focus.
3. Alternate between adjusting R70 and L52 until overall CRT focus is optimized.

## PROCEDURE NO. 2

1. Connect an oscilloscope (DC coupled) between the junction of R71 and C63 (on horizontal circuit card) and signal ground.

## CAUTION

High voltage is present.
2. Adjust the oscilloscope controls until one cycle of the horizontal rate sinewave appears as shown in Figure 1.
3. Adjust the DYNAMIC FOCUS coil, L52 for a minimum sinewave amplitude of not more than 125 volts P.P.

## NOTE

Be sure that the one cycle appearing on the oscilloscope is not a harmonic of the horizontal rate sinewave. This may occur if the DYNAMIC FOCUS coil, L52, is misadjusted to the extent that L 52 will produce the second harmonic. The coil must be adjusted to produce the minimum amplitude of the fundamental frequency only. Confirm the preceding by momentarily connecting the oscilloscope across the primary of T50. Only one cycle or pulse should appear.
4. Observe the center of the CRT display and adjust the FOCUS control, R70, for optimum focus; then record the $D C$ voltage (represented as amplitude " $A$ " in Figure 1) between the DC 0 volt reference and the negative peak of the sinewave.
5. Observe the edges of the CRT display and adjust the FOCUS control, R70, for optimum focus; then record the $D C$ voltage (represented as amplitude " $B$ " in Figure 1) between the DC 0 volt reference and the positive peak of the sine wave.
6. Subtract the negative peak voltage from the positive peak voltage. The difference becomes the voltage value to which the DYNAMIC FOCUS ccil, L52, must be adjusted.
7. While observing the sinewave, adjust the DYNAMIC FOCUS coil, L52, until amplitude "C" (see Figure 1) equals the difference voltage value determined in step 6.
8. While observing the oscilloscope, readjust the FOCUS control, R70, until the negative peak of the sinewave is positioned above the DC 0 volt reference line equal to the voltage value recorded in step 4.

Amplitude " $A$ " - Represents adjusting FOCUS control, R70, for best CRT center FOCUS.
mplitude " $B$ " - Represents adjusting FOCUS control, r70, for best CRT edge FOCUS.

Amplitude " $C$ " - Represents adjusting DYNAMIC FOCUS coil, L52, for final P.P setting that is equal to difference between amplitude " $A$ " and " $B$ ".

NOTE: After amplitude " $C$ " is adjusted, amplitude " $A$ " must be reset to the original voltage value that provided best CRT center FOCUS.


Figure 1. Adjusting Dynamic Focus with an Oscilloscope


## THEORY OF OPERATION

## POWER SUPPLY

(Refer to Figure 2.)
he power supply is a transformer operated, full wave, regulated series pass circuit that maintains a constant output voltage with line input variations of $=12.5 \%$. Depending on how connector S 2 is wired, operation from 115 or

230 volts, $50 / 60 \mathrm{~Hz}$ is possible. Integrated circuit IC150 is the reference amplifier, transistor 0152 is a regulator buffer, transistor Q151 is the regulated output driver, and Q150 is the series pass transistor.

The output voltage, +70 V , appears at the emitter of 0150 . This voltage is divided between R157, R158 and R159. The voltage appearing on the arm of potentiometer R158 (70V ADJ. control) is the reference input to the noninverting input of reference amplifier IC150.


Figure 2. Power Supply Circuit

A temperature compensated zener diode, D154, establishes a fixed reference voltage at the inverting input to 1 C 150. Resistor R156 provides a bias current for D154, which establishes its operating point. Capacitor C153 is a high frequency filter. Operating vo!tage for 1 C150 is derived from a voltage divider consisting of R152 and R153. Components R155 and C151 set the voltage gain of Q152.

An increase in output voltage will result in an increase of voltage at the base of 0152 via the non-inverting input of IC150. The change in base voltage will turn Q152 on harder, reducing its collector voltage. This reduces the forward bias to Q151, which results in less emitter current for Q150. With Q150 conducting less, the output voltage will be lowered.

Components C154 and R160 isolate the power supply common return from chassis (earth) ground. They are only required, however, when the signal input is accompanied by

AC hum. If AC hum is not present, jumper JU150 is used to bypass C154 and R160. Dual-section capacitor C150 provides filtering.

## VIDEO AMPLIFIER

(Refer to Figure 3.)
The linear video amplifier consists of two stages, 0100 and Q101, which are connected in a cascode configuration. This common emitter-common base arrangement greatly reduces the effect of Miller capacity (when compared to a conventional single transistor video amplifier/output stage).

A TTL compatible non-composite video signal, approximately 4.0 volts P-P, is DC coupled to the base of Q100 via R100. Resistor R112 provides proper termination for the nigh frequency input video signal. Capacitor C100 provides high frequency compensation to maintain a flat response when Q100 and Q101 conduct.


Figure 3. Video Amplifier Circuit

During no-signal conditions, Q100 is off. Transistor Q101, however, is forward biased by the 6.2 volts on its base, which is established by zener diode D100. When a video signal is applied to the base of Q100, it conducts, which causes forward biased Q101 to conduct. The resultant output is developed across R104 at the collector of Q101; then DC coupled to the cathode of V1 (CRT) via peaking coil L100 and R113. Resistor R113 isolates Q101 from transients that may occur as a result of CRT arcing. Capacitor C101 shunts to ground high frequency video that may appear on the base of Q101. Peaking coil L100 boosts the high frequencies of the video signal. Capacitor C103 provides additional filtering of the +70 V , while C102 is a high frequency $A C$ bypass capacitor.

## HORIZONTAL SYNC AMPLIFIER

(Refer to Figure 4.)
The horizontal sync amplifier consists of one stage, Q50, which operates as a switch. During a no-signal condition, Q 50 is off. When a positive-going horizontal sync signal, approximately 4.0 volts P-P, is applied (DC coupled) to the base of $\mathbf{Q 5 0}$, it goes into saturation. The amplified output is developed across load resistor R51, approximately 35 V , which forms a voltage divider with R77. The negativegoing horizontal sync pulses are AC coupled to the phase detector circuit via the R-C network consisting of R52 and C68, a high frequency pass filter.


Figure 4. Horizontal Sync Amplifier and Optional Horizontal Sync Delay Circuits

## OPTIONAL HORIZONTAL SYNC DELAY CIRCUIT (Refer to Figure 4.)

This circuit is required when the input TTL level horizontal sync pulse does not have a front porch, which may occur in some systems. (For reference, Figure 5A illustrates a standard horizontal sync pulse with a front porch.) The circuit operates in conjunction with the horizontal sync amplifier, Q50. However, jumpers JU1 and JU2 must be inserted, and resistor R50 removed.

During no-signal conditions, Q55 is off. When a horizontal sync pulse (Figure 5B) is applied to the base of Q55, how. ever, it turns on to saturation. The inverted output (Figure 5C) is developed across load resistor R79 and capacitor C73 charges through R80. When the horizontal sync pulse has completed its period, 055 turns off causing its collector voltage to rise. The base voltage of the horizontal sync amplifier, Q50, also rises turning that device on. Transistor 050 stays on for the duration of the charge on C 73 , which discharges through R80 and the base-emitter junction of Q50.

The time delay between the turn-on of Q55 and turn-on of 050 is approximately 2.0 to 5.0 uS, or the time duration (width) of one horizontal sync pulse without a front porch (Figure 5D). Resistor R82 is for current limiting to the base of Q55. Diode D57 protects Q 50 from reverse breakdown.


Figure 5. Horizontal Sync Delay Circuit Waveforms

## PHASE DETECTOR

(Refer to Figure 6.

The phase detector consists of two diodes (D50 and D51) in a keyed clamp circuit. Two inputs are required to generate the required sutput, one from the horizontal sync


Figure 6. Phase Detector and Horizontal Oscillator Circuits
amplifier, Q50, and one from the horizontal output circuit, Q54. The required output must be of the proper polarity and amplitude to correct phase differences between the input horizontal sync pulses and the horizontal time base. The horizontal output (Q54) collector pulse is integrated into a sawtooth by R56 and C69. During horizontal sync time, diodes D50 and D51 conduct, which shorts C69 to ground. This effectively clamps the sawtooth on C69 to ground at sync time. If the horizontal time base is in phase with the sync (waveform A), the sync pulse will occur when the sawtooth is passing through its $A C$ axis and the net charge on C69 will be zero (waveform B). If the horizontal time base is lagging the sync, the sawtooth on C69 will be clamped to ground at a point negative from the AC axis. This will result in a positive DC charge on C69 (waveform C). This is the correct polarity to cause the horizontal oscillator to speed up to correct the phase lag. Likewise, if the horizontal time base is leading the sync, the sawtooth on C69 will be clamped at a point positive from its AC axis. This results in a net negative charge on C69, which is the required polarity to slow the horizontal oscillator (waveform D). Components R55, C52, R58 and C53 comprise the phase detector filter. The bandpass of this filter is chosen to provide correction of horizontal oscillator phase without ringing or hunting. Capacitor C50 times the phase detector for correct centering of the picture on the raster.

## HORIZONTAL OSCILLATOR

(Refer to Figure 6.)
The horizontal oscillator consists of Q51, which is employed as a modified type of Hartley oscillator. The operating frequency of this oscillator is sensitive to its base input voltage. This permits control by the output of the phase detector. Resistor R57 provides DC bias to turn on Q51 and start the oscillator. The free-running horizontal frequency is adjusted with the HORIZ. SET coil, L50,
which along with C54 are the frequency determining components. Capacitor C55 and resistor R60 are feedback components for the oscillator circuit.

## HORIZONTAL PULSE SHAPER \& DRIVER (Refer to Figure 7.)

Transistor Q52 is a buffer stage between the horizontal oscillator and horizontal driver. It provides isolation for the horizontal oscillator as well as a low impedance drive for the horizontal driver. Components R62 and C56 form a time constant that shapes the oscillator output to the required duty cycle, approximately $50 \%$, to drive the horizontal output circuitry. The horizontal driver stage, 053, operates as a switch to drive the horizontal output transistor (O54) through T50. Because of the low impedance drive and fast switching times furnished by 052 , very little power is dissipated in Q53. Components R66 and C57 provide damping to suppress ringing in the primary of T50 when 053 goes into cutoff. (Reference Figure 8 - Resistor R68 provides current limiting for 053 while C 58 is an AC bypass capacitor.)


Figure 7. Horizontal Pulse Shaper and Driver Circuits


Figure 8. Horizontal Output Circuit

## HORIZONTAL OUTPUT

(Refer to Figure 8.)
The secondary of T50 provides the required low drive impedance for Q54. Components R67 and C59 form a time constant for fast turn-off of the base of Q54. Once during each horizontal period, 054 operates as a switch that connects the supply voltage across the parallel combination of the horizontal deflection yoke and the primary of the high voltage transformer. The required sawtooth deflection current (through the horizontal yoke) is formed by the L-R time constant of the yoke and primary winding of the H.V. transformer, T51. The horizontal retrace pulse charges C62 through D54 to provide operating voltage for G2 of the CRT. Momentary transients at the collector of O54, should they occur, are limited to the voltage on C62 since D54 will conduct if the collector voltage exceeds this value.

The damper diode, D53, conducts during the period between retrace and turn on of Q54. Capacitor C65 is the retrace tuning capacitor, while C61 blocks DC from the deflection yoke. Coil L51 is a magnetically biased linearity coil that shapes the deflection current for optimum trace linearity. Coil L53 is a series horiz. width control. Comnents R72 and C70, C64 and R75 are damping network ,mponents for the horizontal linearity (L51) and width (L53) controls. Capacitor C71 couples horizontal sync pulses from pin 7 of T51 to diode clamp D55, which maintains the -70 V reference voltage.

## OPTIONAL DYNAMIC FOCUS CIRCUIT <br> (Refer to Figure 9.)

Due to the geometry of a CRT, the electron beam travels a greater distance when deflected to a corner as compared to the distance traveled at the center of the CRT screen. As a result of these various distances traveled, optimum focus can be obtained at only one point. For general applications, an adequate adjustment can be realized by setting the focus while viewing some point mid-way between the center of the CRT screen and a corner, thus optimizing the overall screen focus. When an application requires a tighter specification, one of the simplest methods for improvement is to modulate the focus voltage at a horizontal sweep rate. Now optimum focus voltage is made variable on the horizontal axis of the CRT, which compensates for the beam travel along this axis.

The AC component focus voltage is developed by a series resonant circuit consisting of L52 and C63. This voltage is an 80 V P-P horizontal rate pulse coupled from a tap on the horizontal output transformer, T51, via C67. The normal DC component of the G4 focus voltage is set by adjusting the FOCUS control, R70. When the DYNAMIC FOCUS coil, L52, is optimized for best edge focus, a sinusoidal voltage of approximately 200 V P-P is developed across C63. This mixed $A C$ and $D C$ voltage results in a waveform of proper phase and amplitude, which is coupled through isolating resistor R108 to the CRT focus anode.


Figure 9. Simplified Dynamic Focus Circuit Diagram

## VERTICAL SYNC AMPLIFIER

(Refer to Figure 10.)
The vertical sync amplifier consists of one stage, Q 1 , which operates as a switch. During no-signal conditions, Q1 is off. When a positive-going vertical sync signal, approximately 4.0 volts P-P, is applied (direct coupled) to the base, Q1 goes into saturation. The amplified output is developed across load resistor R3 to approximately 11 volts. Jumpers JU3, JU4, and JU5 are inserted depending on the polarity of the input vertical sync pulse; TTL NEG for negativegoing and TTL POS for positive-going.

## SYNC SHAPER

(Refer to Figure 10.)

The negative-going vertical sync pulses (from Q1) are direct coupled to the non-inverting input of the sync shaper stage, IC1. The combined action of an integrating network, consisting of C1, C2, C3, R5, R6, and R7, removes high frequency noise from the vertical sync pulses. Capacitor C3 performs the actual integrating, while resistors R5-R7 provide biasing for IC1. Capacitors C1 and C2 provide a bypass function.

## VERTICAL OSCILLATOR

(Refer to Figure 11.)

The negative-going vertical sync pulses are AC coupled (C4) to the gate of a programmable unijunction transistor device, D1. This device turns on with each negative-going sync pulse applied to its gate. This action permits C6 and C7 to discharge very rapidly; then recharge slowly during the period that a sync pulse is not applied to the gate. The recharge path for C6 and C7 is through R12 and R13. As soon as the next sync pulse is applied to the gate of D1, C6 and C7 discharge very rapidly again. This sequence of events produces a positive-going ramp or sawtooth waveform at the anode of D1.

When no vertical sync pulses are connected to the monitor, vertical oscillator D1 is kept free-running to maintain a raster on the CRT. This is accomplished by biasing the gate of D1 in conjunction with the charge and discharge action of C6 and C7. Resistors R9 and R8 provide the proper bias for D1, which also determines the repetition rate for the charge and discharge action of C 6 and C 7 .

In addition, during no-signal conditions, components R22 and D2 (in conjunction with D1), provide a small incremental voltage above ground to compensate for the baseemitter voltage drop of the vertical driver, Q3. This is necessary to keep the vertical output stage, Q 4 , from being driven into cutoff, which could result in distorted vertical linearity.

## VERTICAL DRIVER

## (Refer to Figure 11.)

The positive-going sawtooth waveform, from the anode of D1, is direct coupled to the base of vertical driver Q3, which operates as an emitter follower. The sharp fall time of the sawtooth is a result of the rapid discharge of C6 and C7 through D1. The amplitude of the sawtooth is varied with the HEIGHT control, R12.


Figure 10. Vertical Sync Amplifier and Sync Shaper Circuits


Figure 11. Vertical Oscillator/Driver and Optional StepScan Amplifier Circuits


The output sawtooth from the emitter of $Q 3$ is direct coupled to the base of vertical output stage, Q4. Part of this sawtooth waveform, however, is also coupled back to the junction of C6 and C7 via R18 and VERT. LIN. control R17 for proper shaping. Since this path is resistive, the waveform will be integrated into a parabola waveform by C7 (waveform A). This results in a predistortion of the drive sawtooth (waveform C). (Waveform B illustrates the drive sawtooth without parabola shaping.) Parabola shaping is necessary to compensate for the non-linear charging of C 6 and C 7 . An additional path for phase compensation is provided through C12 and R19.

## VERTICAL OUTPUT

(Refer to Figure 12.)
The positive-going sawtooth waveform from the emitter of Q3 is applied to the base of vertical output stage, Q4, which conducts only during the ramp, or rise time, of the sawtooth waveform. The inverted ramp output (collector current) is the vertical trace period, which is AC coupled
(via C14) to the vertical deflection yoke winding. The same collector current output is also applied to L1, which builds up a large electromagnetic field. This field will collapse very rapidly when Q4 turns off during the retrace time of the waveform applied to the base of Q4. The back EMF is in the form of a high voltage positive pulse, whose duration represents the vertical retrace period. To limit this pulse to a safe value, a varistor is connected across L1, with R26 providing damping.

Except for the vertical output stage, Q4, the vertical circuitry operates from a +12 volt source, which is derived from the +70 volt source. Resistor R27 drops the +70 volt source to the required +12 V . Zener diode D3 holds the +12 V constant while C11 provides additional filtering.

## OPTIONAL VERTICAL BLANKING AMPLIFIER CIRCUIT

(Refer to Figure 12.)

The vertical blanking amplifier circuit is for systems that desire to blank the beam during the vertical retrace period.

Transistor Q9 turns on only when a high voltage positive pulse is applied to its base. (This positive pulse is generated for the retrace period each time the vertical output stage, Q4, iurns off.) Components R35, C17 and R36 form a voltage divider to protect the base input of Q9. The inverted collestor oltput is developed across R37, which forms a voltage divider with R38. The amplitude of the negative blanking pulse is approximately 30 volts $P-P$, which is $A C$ coupied by C104 to G1 of the CRT. Capacitor C105 is a high frequency bypass for G1.


Figure 12. Vertical Output and Optional Vertical Blanking Amplifier Circuits

## STEPSCAN FUNCTION

With existing logic, the number of characters that can be displayed is limited by logic speed. Anything that increases the speed at which the logic must work, will allow an increase in the number of characters displayed.

When a video monitor is used as a data display, the system bandwidth required (and logic speed) increases in direct proportion to the number of scan lines displayed. Since no data is written in the blank spaces between character rows, a method is required to speed up vertical deflection in the blank spaces to decrease bandwidth requirements. This makes the blank space height less dependent on scan time, allowing time to display more characters. This is accomplished by "stepping" the reference sawtooth between character rows so that a row to row space of from 3 to 5 horizontal lines equivalent height can be displayed in the time it takes to deflect one horizontal line. This is illustrated in Figure 13.

## OPTIONAL STEPSCAN CIRCUIT

(Refer to Figure 11.)
This circuit requires an external (approximately 4.0 volts P.P) TTL positive-going pulse. These pulses are applied to the emitter of the StepScan Amplifier, Q2, which is turned on when the emitter voltage exceeds the base voltage. The +12 volts stored on C5 is applied through Q2, R11 and R14, to the sawtooth forming capacitors C 6 and C 7 . This momentarily increases the charge rate of $C 6$ and $C 7$, and the resultant action produces the stepping sawtooth shown as waveform D. The rate at which the vertical oscillator steps is determined by the repetition rate of the incoming StepScan pulses. The slope (charge rate) of the stepped portion of the sawtooth is adjustable with the STEP ADJ. control, R11, which varies the spacing from 3 to 5 horizontal scan lines. With the vertical sawtooth thus modified, the collector current of Q14 and, therefore, the yoke vertical deflection current will be "stepped" during the line between character rows chosen.
(PARTIAL VERTICAL FRAME SHOWN)


Figure 13. Displaying Characters on a Monitor with StepScan


Vertical/Video Circuit Card (Component View)




Horizontal Circuit Card (Component View)


Rear Chassis View - Typical of M3000/M4000


Horizontal Circuit Card (Solder View)
REPLACEMENT PARTS LIST

| REF. NO. | PART NUMBER | DESCRIPTION | REF. NO. | PART NUMBER | DESCRIPTION |
| :---: | :---: | :---: | :---: | :---: | :---: |
| VERTICAL/VIDEO CIRCUIT CARD (COMPLETE): HORIZONTAL CIRCUIT CARD (COMPLETE): POWER SUPPLY CIRCUIT CARD (COMPLETE): Order by Model No. and Description |  |  | C61 | 8S10571A23 | $\begin{aligned} & 0.5610 \%, 250 \mathrm{~V} \text {; Polyprop } \\ & \text { (M3000-100,200,300,400) } \end{aligned}$ |
|  |  |  | C61 | 8S10299B27 | 0.82 10\%, 400V; Mtiz Poly Carb (M4000-100, 200) |
|  |  |  | C62 | 8S10212A11 | 1.0 10\%, 630V; Mtiz Mylar |
|  |  |  | C63 | 8S10571A06 | . $015 \%, 1200 \mathrm{~V}$; Polyprop |
| CAPACITORS: |  |  | C64 | $215180 \mathrm{B51}$ | . 001 10\%, Z5F, 500V: Cer. Disc |
| (ALL VALUES ARE IN MICROFARADS UNLESS OTHERWISE NOTED.) |  |  | C65 | 8S10571A04 | .0068 5\%, 1200V; Polyprop (M3000-100, 200, 300, 400) |
| C1 | 215180B87 | 220 pF 10\%, X 5 F, 500V ; Cer. Disc | C65 | 8S10571A05 | .008 10\%, 1200V; Polyprop $(\mathrm{M} 4000-100,200)$ |
| C2 | 21S180E60 | . $11+80-20 \%, 25 \mathrm{~V}, 50 \mathrm{~V}$; Cer. Disc | C65 | 8S10212B53 | $0.47 \text { 10\%, 630V; Mtlz Mylar }$ |
| C3 | 21S180C50 | 100 pF 5\%, NPO, 500V ; Cer. Disc | C67 | 8S10212820 | 0.47 10\%, 400V; Mitz Poly |
| C4 | 8S10212D52 | $0.110 \%, 100 \mathrm{~V}$; Mtiz Poly | C68 | 215131625 | 330 pF 10\%, X5F, 500V; Cer. Disc |
| C5 | 8S10191891 | . 047 10\%, 250V, Polyester | C69 | 215180C41 | . 0027 10\%, Z5F, 500V; Cer. Disc |
| C6. 7 | $8 S 10191 B 67$ | 0.22 10\%, 250V; Polyester | C70 | 21S180B72 | 470 pF 10\%, Z5F, 500V; Cer. Disc |
| C11 | 23S10255A69 | 4.7, 100V; lytic | C71 | 8S10191807 | .047 10\%, 400V; Polyester |
| C12 | 8S10212C08 | 0.22 10\%, 100V; Polyester | C72 | 23S10255B28 | 4.7, 100V: lytic |
| C14 | 23S10255A60 | 100, 63V ; lytic | C73 | 215180F02 | 180 pF 10\%, Z5F, 500V; Cer. Disc |
| C17 | 8S10191891 | . 047 10\%, 250V; Polyester | C74 | 21S180855 | 22 pF 10\%, NPO, 500V; Cer. Disc |
| C50 | 215180 C 02 | 10 pF , NPO, 500V; Cer. Disc | C100 | 21S180E50 | 120 pF 5\%, NPO; Cer. Disc |
| C51 | 215180 D 34 | . 005 20\%, 25F, 1 kV ; Cer. Disc | C101. 102 | $215180 E 60$ | $.01+80-20 \%, 25 \mathrm{~V}, 50 \mathrm{~V} \text {; Cer. Disc }$ |
| C52 | 23S10229A32 | 1.0 $+40-20 \%$, 16 V ; iytic | Ci03 | 23S10255A69 | 4.7.100V: Ivtic |
| C53 | 8S10191890 | . 033 10\%, 250V; Polyester | C104 | 8S10191C02 | $0.110 \%, 250 \mathrm{~V}$ : Polvester |
| C54 | 8S10299A32 | . 01 10\%, 400V; Poly Carb | C105 | 21S180A62 | . 005 20\%, Z5V, 500 V ; Cer. Disc |
| C55 | 8S10299A33 | . 0082 10\%, 100V: Poly Carb | Ci06 | 23S10255826 | 4.7, 63V; lytic |
| C56 | 8S10191B98 | . 01 10\%, 250V; Polvester | C150A/B | 23S10255B71 | 400/125V, 600/100V; lytic |
| C57 | 215180851 | . $00110 \%, \times 5 \mathrm{~F}, 500 \mathrm{~V}$; Cer. Disc | C151 | 215180E60 | . $01+80-20 \%, 25 \mathrm{~V}, 50 \mathrm{~V}$; Cer. Disc |
| C58 | 215180 E 60 | . $01+80-20 \%, Z 5 F, 50 \mathrm{~V}$ : Cer. Disc | C. 53 | 215180851 | . 001 10\%, X5F, 500V; Cer. Disc |
| C59 | 23S10255881 | 150, 10V; lytic | C154 | 215180002 | 0.1+80-10\%, 100V; Cer. Disc |

REPLACEMENT PARTS LIST (Cont'd)

| REF. <br> NO. | PART <br> NUMBER | DESCRIPTION | REF. NO. | PART NUMBER | DESCRIPTION |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DIODES: |  |  | R70 | 18C25218A14 | Control, Focus 2 Meg. |
|  |  |  | R104 | $17 \mathrm{S647132}$ | 1.2k 10\%, 5W |
| D1 | 485137638 | Programmable UJT, MPU-6027; Vert. Osc. | R106 | 18D25245A22 | Control, Master Brightness 250k |
|  |  |  | R111 | 18D25212A39 | Control, Brightness 200k |
| D2 | 48S191A05 | Rectifier, Silicon; A05 | R158 | 18D25245A21 | Control, 70 V Adjust 2.5 k |
| $\begin{aligned} & \text { D3 } \\ & \text { D. } 4,50,51 \end{aligned}$ | 48D10641B12 | Diode, Zener |  |  |  |
|  | 48D67120A11 | Diode, Low Power; A11 | TRANSFORMERS: |  |  |
| D53 | 48S134921 | Diode, D1D; Damper |  |  |  |
| D54 | 485134978 | Diode, D1K; Pulse Lim. | T50 | 25D25221A05 | Transformer, Horiz. Driver |
| D55 | 485134921 | Diode, D1D | T51 | 24D25240B11 | Transformer, High Voltage |
| $\begin{aligned} & \text { D56 } \\ & \text { D57-59 } \end{aligned}$ | 485137622 | Diode, Silicon, D9N; H.V. Rect. |  |  | (M3000-100,200,300,400) |
|  | 48D67120A11 | Diode, Low Power; A11 | T51 | 24D25240813 | Transformer, High Voltage |
| D 100 | 48S10813A01 | Diode, Zener 6.2V 5\% (1N5234B) |  |  | (M4000-100,200) |
| D150-153 | 48S191A05 | Rectifier, Silicon; 91A05 | T150 | 25D68164A33 | Transformer, Power |
| D154 | 48S10813A02 | Diode, Zener 5.1V |  |  |  |
|  |  |  | MISC. | TRICAL PART |  |
| FUSES: |  |  |  |  |  |
| F150 | 65S139424 | Fuse, Slow Blow 1.0 Amp. | V1 | 96S233A01 | 12" CRT; Type ST5449A (M3000-100,200,300,400) |
|  |  |  | V1 | 96S219A01 | 15" CRT; Type ST4730C |
| INTEGRATED CIRCUITS: |  |  |  |  | (M4000-100, 200) |
| IC1 | $51510732 \mathrm{A01}$ | Integrated circuit, T3F; Sync Shaper | MECHANICAL PARTS: |  |  |
| - IC150 | 51S10732A01 | Integrated circuit, T3F; Ref. Ampl. |  | $\begin{aligned} & 42 \mathrm{~B} 25158 \mathrm{C} 01 \\ & 42 \mathrm{~S} 10240 \mathrm{~A} 07 \end{aligned}$ | Clamp, Deflection Yoke Clamp (Mt. C150A/B) |
| COILS/CHOKES: |  |  |  | 42S10122A12 | Clip, Fuse |
|  |  |  |  | 42D25298A03 | Connector, Anode |
| L1 | 25D25221A13 | Choke, Vert. | P3 | 28S10586A20 | Connector, 2-Contact |
| L. 2 | 24D25261B01 | Yoke, Deflection (M3000-100, | P4, 5 | 28S10586A25 | Connector, 3-Contact |
|  |  | 200, 300, 400) | P6 | 28S10586A 14 | Connector, 3-Contact |
| L2 | 24D25261A08 | Yoke, Deflection (M4000-100, | P7 | 28S10586A21 | Connector, 4-Contact |
|  |  | 200) | P8 | 28S10586A14 | Connector, 3-Contact |
| L50 | 24D68822A01 | Coil, Horiz. Set |  | 14S10550A02 | Cover, Transistor (Q54) |
| L51 | 24D25248A12 | Coil, Horiz. Lin. | S2 | 15S10183A77 | Housing, Receptacle; 6-Contact |
| L52 | 24D25248A01 | Coil, Dynamic Focus |  |  | (Less Contacts) |
| L53 | 24D25248B11 | Coil, Horiz. Width |  | 39S10184A64 | Contact, Receptacle |
| L. 100 | 24D25248A13 | Coil, Peaking 4.7 uH 10\% |  |  | (4 Req'd for S2) |
|  |  |  | S3 | 15S10183A94 | Housing, Receptacle; 2-Contact |
| TRANSISTORS: |  |  |  |  | (Less Contacts) |
| Q1 | 48S137172 | Vert. Sync Ampl; A6J |  | 39S10184A72 | Contact, Receptacle (2 Req'd for S3) |
| Q2 | 485137127 | Step Ampl; P2S | S4 | 15S10183A87 | Housing, Receptacle; 3-Contact |
| Q3 | 485137639 | Vert. Driver; MPS-A13 |  |  | (Less Contacts) |
| Q4 | 485137596 | Vert. Output; B2V |  | 39S10184A72 | Contact, Receptacle (3 Req'd |
| 09 | 485137172 | Vert. Blank Ampl; A6J |  |  | for S4) |
| 050 | 485137172 | Horiz. Sync Ampl; A6J | S5, 6 | 15S10183A87 | Housing, Receptacle 3-Contact |
| Q51 | 485137172 | Horiz. Osc.; A6J |  |  | (Less Contacts) |
| 052 | 485137127 | Horiz. Pulse Shaper; P2S |  | 39S10184A72 | Contact, Receptacle (2 ea. |
| 053 | 485137093 | Horiz. Driver; A5F |  |  | Req'd for S5 \& S6) |
| Q54 | 485137570 | Horiz. Output; B2L | S7 | 15S10183A88 | Housing, Receptacle; 4-Contact |
| 055 | 485137172 | Horiz. Sync Delay; A6J |  |  | (Less Contacts) |
| Q100 | 485134952 | Video Driver; A2J |  | 39S10184A72 | Contact, Receptacle (4 Req'd |
| Q101 | 485137093 | Video Output; A5F |  |  | for S7) |
| Q150 | 485137368 | Regulator; A8W | S8 | 15S10183A87 | Housing, Receptacle; 3-Contact |
| Q151 | $48 S 134952$ | Reg. Driver; A2J |  |  | (Less Contacts) |
| 0152 | 485137636 | Ref. Ampl; 7636 |  | 39S10184A72 | Contact, Receptacle (3 Req'd for S8) |
|  |  |  |  | 14A25393A01 | Insulator, Hi-Voltage Standoff |
| RESISTORS/CONTROLS: |  |  |  | 14A562353 | Insulator, Transistor (Q150,054, Q4) |
|  |  |  |  | 2S10054A25 | Nut, Spring |
| NOTE | Only power or special resistors are listed. Use the description when orciering standard values of fixed carbon resistors up to 2 watts. |  |  | 3S136050 | Screw, 6-20×1/2" Clutch Head (Mt. Q150, 054, Q4) |
|  |  |  |  | 26B25137B01 | Shield, Coil (L50) |
|  |  |  |  | 26B25348A01 | Shield (Mt. w/L1) |
| R11 | 18D25245417 | Control, Step Adjust 25k |  | 9D25470A02 | Socket, CRT (Incl. leads and |
| R12 | 18D25245A22 | Control, Height 250k |  |  | resistors R113-R110 \& R81) |
| R17 | 18D25245A22 | Control, Vert. Lin. 250k |  | 9C63825A03 | Socket, Transistor (0150, Q54, Q4) |
| R25 | 6S10201A04 | Varistor, VDR 1 mA |  | 41065937A01 | Spring, Special; CRT Aquadag Gnd |
| R68 | 17510130807 | 1.5k 10\%, 3W |  | 66C68497A03 | Tool, Adjust |




[^0]:    * Specifications subject to change without notice.

