Data General Corporation Technical Manual

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Nova 1210

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# DATA GENERAL TECHNICAL MANUAL

# NOVA 1210 COMPUTER

Models 8131, 8132, 8133, 8134 8135, 8136, 8137, 8138

Ordering No. 015-000010

Copyright (C) 1972, Data General Corporation Printed in U.S.A. Rev. 01 11 August 1972 INTRODUCTION 0 CENTRAL PROCESSOR **OPERATORS CONSOLE** K POWER SUPPLY Ρ MEMORY INSTALLATION MAINTENANCE **REFERENCE TABLES** Т (

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## TABLE OF CONTENTS

#### SECTION O

#### INTRODUCTION

Page
------

THE NOVA 1210 COMPUTER	O-1
THIS MANUAL	O-2

#### SECTION C

#### THE CENTRAL PROCESSOR UNIT

INTRODUCTION C-1
THE CONTROL UNIT
Major States. C-1   TS Cycles. C-2   Timing Generator Cycles. C-2   The Processor Timing Generator. C-2   The Accumulator Timing Generator. C-2   The Memory Timing Generator. C-2   The Memory Timing Generator. C-2
CPU DATA PATHS
Registers.C-5Program Counter (PC).C-5Instruction Register (IR and MBC).C-5CPU Interface Register (MBO).C-5Shift Buffer (ACB).C-5Accumulators (AC0, AC1, AC2, AC3).C-5Data Flow.C-5Nibble Transfers.C-5Instruction Overlapping.C-6Data Buses.C-6
THE FLOW AND TIMING DIAGRAMS C-6
FETCH. .C-8   ALC. .C-10   EFA. .C-12   I/O. .C-15   DE FER. .C-16   EXEC. .C-20   DCH. .C-20   PI. .C-30   F COM. .C-33

REFERENCESC-	-	•6	5	
--------------	---	----	---	--

## SECTION K

## THE OPERATOR'S CONSOLE

P	'a	g	e
-	u	ъ	~

INTRODUCTION
CONSOLE LIGHTS AND SWITCHES K-1
The Console ADDRESS Lights.K-1The Console DATA Lights.K-1The Console Operational Indicators.K-1The Console Switch Register.K-2The Console Control Switches.K-2The Console Rotary Switch.K-2
REFERENCES

#### SECTION P

## THE POWER SUPPLY

INTRODUCTION	P-1
POWER SUPPLY CIRCUITS	P-1
The 30V Unregulated Supply. I   The Series Pass Switching Regulators. I   The Fuses. I   The Power Fail Module. I	?-1 ?-1 ?-1 ?-1
REFERENCES	2-1

#### SECTION M

#### THE MEMORY

A REVIEW OF CORE MEMORIES M	[-1
DATA GENERAL'S CORE MEMORIES M	[-2
The Memory Select Logic M	[-2
REFERENCES M	[-2

#### SECTION I

#### INSTALLING THE COMPUTER

Page

INTRODUCTION I-1
PLACING THE COMPUTER I-1
UNPACKING THE COMPUTER I-1
PACKING THE COMPUTER
ASSEMBLING THE COMPUTER I-3
Installing or Removing Boards I-3   Rack Mounting The Computer I-5
CABLING ASSEMBLIES TOGETHER I-5
Types of Cables.I-5I/O Cables.I-5Device Cables.I-5Internal Cables.I-5Interdevice Cables.I-5Adapter Cables.I-5Cabling The System.I-8
REFERENCESI-8

#### SECTION N

#### MAINTAINING THE COMPUTER

INTRODUCTION
FIELD SERVICE ORGANIZATION N-1
Field Service Programs. N-1   On Call Service Contract. N-1   Warranty Extension Service Contract. N-1   Hourly Service. N-1   General Terms and Conditions. N-1
TRAINING ORGANIZATION N-2
Mainframe Maintenance Course.N-2Fundamentals of Mini-Computer Programming.N-2Basic Programming.N-2Advanced Programming.N-2
PREVENTIVE MAINTENANCE
HOW TO TEST THE COMPUTER N-7

#### **REFERENCE TABLES**

	Page
SIGNAL LIST	T1-1
ABBREVIATIONS	.T2-1

#### LIST OF ILLUSTRATIONS

Figure	Title	Page
O-1	Exploded View of The Nova 1210 Computer With Central Processor and Memory Cards Removed	<i>.</i> O-1
O-2	Block Diagram of The Basic Nova 1210 Computer	. 0-3,0-4
O-3	Nova 1210 Hardware Documentation	. O-5
C-1	Timing For The Processor Timing Generator During All Major States Except Fetch or Key	. C-2
C-2	Timing For The Processor Timing Generator During Fetch or Key	.C-3
C-3	Timing For The Accumulator Timing Generator	.C-3
C-4	Timing For The Memory Timing Generator	.C-4
C-5	The Nova 1210 Central Processor	.C-7
C-6	Data Channel Signals	. C-36
C-7	Deposit Timing Diagram	.C-37
C-8	Examine AC1 Timing Diagram	.C-38
C-9	ADD0, 1, SKP Timing Diagram	.C-39
C-10	MOV0, 0 Timing Diagram	.C-40
C-11	Timing Diagram For Both The ISZ And DSZ Instructions	.C-41
C-12	LDA Timing Diagram	. C-42
C-13	STA Timing Diagram	C-43
C-14	JMP @ 100 Timing Diagram	C-44
C-15	JSR @ 20 Timing Diagram	. C-45
C-16	I/O Input Timing Diagram	C-46
C-17	I/O Output Timing Diagram	.C-47

## LIST OF ILLUSTRATIONS (Continued)

Figure	Title	Page
C-18	PI Timing Diagram	C-48
C-19	Data Channel Increment Timing	C-49
C-20	Data Channel In Timing	C-49
C-21	Data Channel Out Timing	C-50
C-22	Data Channel Out Followed By Data Channel In Timing	C-50
K-1	The Console	K-1
K-2	The CPU Key Sequence Timing Diagram	K-2
K-3	Key, KEYM and Manual Flow Diagrams	К-4
P-1	Simplified Schematic of The +5Vdc Series Switching Regulator	P-3
P-2	Simplified Schematic of The +15Vdc Series Switching Regulator	P-4
M-1	Simplified Schematic of a Memory Core	M-1
M-2	Simplified Schematic of The Core Memory's Sense and Inhibit Lines	M-2
M-3	Core Memory	M-3
M-4	Wiring Up The Select Logic of 1K and 2K Boards	M-4
M-5	Wiring Up The Select Logic of 4K and 8K Boards	M-5
I-1	The Nova 1210 Shipping Kit	I-2
I <b>-2</b>	Nova 1210 Board Slots	I-3
I-3	Rack Mounting Hardware For The Nova 1210	I-4
I-4	Sketch of The Nova 1210 Cabling Schemes	I-6

#### LIST OF TABLES

Number	Title	Page
C-1	Adder and Multiplexer Control Signals During EFA Instructions	.C-34
C-2	Adder Control Signals During ALC Instructions (TS3)	C-34
C-3	Carry Chart For ALC Instruction	C-35
C-4	Memory Reference Instruction Decoding Chart	C-35
K-1	Control Switch Decoding To The Instruction Register	.K-3
K-2	Backpanel Connections To The Console Through POA	K-5
P-1	Output Voltages of The Nova 1210 Power Supply	P-2
<b>P-2</b>	Output Signals of The Nova 1210 Power Fail Module	.P-2
M-1	External Memory Signals	M-6
I-1	The Nova 1210 Electrical, Mechanical and Environmental Specifications	I-1
I-2	P3 Interconnections for Nova 1210	.I-7
N-1	Preventive Maintenance Check List	N-3
N-2	Recommended Maintenance Tool Kit	N-4
N-3	The Nova 1210 Diagnostics	N-5

#### SECTION O

#### INTRODUCTION

#### THE NOVA 1210 COMPUTER

The Nova 1210 computer shown in Figure O-1 consists of a power supply-backpanel assembly and a console assembly mounted on a chassis into which plug up to four 15" X 15" PC boards. The chassis includes a frame, a fan, a filter, a power transformer and a power switch assembly; the power supply backpanel includes the power supply and four sets of edge connectors mounted on an etched PC board. The console includes a frame, front panel and PC board which holds the switches, lights and associated logic. Each basic Nova 1210 includes a Central Processor module and any one of four types of Memory modules; 1K, 2K, 4K or 8K. A table top assembly is also available but not shown.



Figure O-1 Exploded View of The Nova 1210 Computer With Central Processor and Memory Cards Removed

The Central Processor, Console, Memories and Controllers communicate with each other along 16 bit buses called MEM, MBO and IN-OUT as shown in Figure O-2. MEM transfers information from Memory or the Console to the MBO or Instruction registers; MBO transfers information from the MBO register to the Console and Memories, and IN-OUT transfers information between the Memory's MB register and peripheral controllers. In the Nova 1210 proper all these data paths and their associated control signals travel along etched tracks on the backpanel to the board's edge connectors and to a plug in the console's PC board.

#### THIS MANUAL

This manual explains how the basic Nova 1210 works, how it is installed and how it is maintained. It is divided into 8 sections:

Section O introduces the machine and this manual;

Section C explains how the Central Processor works;

Section K explains how the operator's Console works;

Section P explains how the Power Supply works;

Section M explains how the Memories work;

Section I explains how to install the computer;

Section N explains how to maintain the computer;

Section T has two reference tables - a signal list and a list of expanded abbreviations. The signal list traces the source and destination of each signal in the Central Processor and the Memory. Source signals are listed alphanumerically by name. Each source signal originates at the output pin (PIN) of an integrated circuit (CHIP) which is called out on a drawing (DWG) at a grid reference (GRID). Each signal is wired to one or more ICs which themselves originate more signals, or (FUNCTIONS), whose names and locations are listed in the DESTINATION column beside their originating signal. Drawing numbers are identified by the last two numbers of the print followed by a hyphen followed by their sheet number (s).

#### **RELATED DOCUMENTS**

Figure O-3 lists the engineering prints and manuals which describe the basic computer. The manual "How To Use The Nova Computers" explains how to program the machine. The manual "The I.C. User's Guide" gives logic diagrams and truth tables for the I.C.s used in Data General's machines.



# Figure O-2 Block Diagram of The Basic N 1210 Computer



Figure O-3 1210 Hardware Documentation

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#### SECTION C

#### THE CENTRAL PROCESSOR UNIT

#### INTRODUCTION

The central processor unit (CPU) used in this computer is a binary, 2's complement, fixed word length, parallel/serial, digital, automatic processor. It takes up to 32K words of  $1.2\mu \sec co$ -ordinate-addressed core memory of 16 bits per word. It has 7 sixteen bit hardware registers: four accumulators (AC0, AC1, AC2 and AC3); a programtransparent shift buffer (ACB); a program-transparent memory buffer (MBO); and one 15 bit program counter (PC). All internal data paths are four bits (or one "nibble") wide, so each internal transfer takes four steps; all three external data paths or buses, (MEM, MBO and IN-OUT) are 16 bits wide so each external transfer takes one step.

There are three classes of instructions; memory reference (EFA), input-output (I/O) and arithmetic and logic (ALC). There are three modes of addressing; absolute, index (to AC2 or AC3) and relative (to PC).

Peripheral devices can interrupt the processor and transfer data to or from its accumulators via the I/O instruction set, or simply use the processor's high speed data channel directly to memory.

The CPU is contained on a single 15" by 15" PC board which is inserted into the first slot of the computer's chassis. Power is supplied by the chassis' power supply.

#### THE CONTROL UNIT

The CPU is a synchronous processor for which time is broken up by two clocks into discrete, fixed periods. The two clocks are derived from a 13.333Mhz crystal oscillator which is divided by two. One clock, called MEM CLK is always running; the other, called CPU CLK is gated by three signals RUN, STUTTER and WHOA. RUN is a control flip-flop which stops the processor when it resets; STUTTER inhibits the clock for one cycle and WHOA is used by certain options like the multiply divide to slow the machine down. With these clocks the Control generates eight major states and two levels of minor states called timing state (TS) cycles and timing generator (TG) cycles.

#### Major States

Major states define what type of memory function is under way. The designated major state of the machine is set at the beginning of each memory cycle and remains set throughout that memory cycle. There are eight major states; Fetch, Defer, Execute, PI,DCH,Key, Keym, and a "dummy" state during which none of the other states are set.

- 1. Fetch occurs when the next word to be read from memory is to be treated as an instruction.
- 2. Defer occurs when the next word from memory is to be treated as the address of an operand or instruction, i.e., during indirect addressing.
- 3. Execute occurs when the next word from memory is to be treated as an operand. Programmed I/O operations also set Execute, but the memory is not allowed to run.
- 4. PI occurs during a program interrupt when:
  - the contents of the PC are stored in location 0
  - the next major state is set to Defer
  - A JMP instruction is forced into the Instruction Register
  - the next address executed is in location 1, which should be set to the starting address of the service routine.
- 5. DCH occurs when the next memory cycle is to be a direct transfer between an I/O device and Memory.
- 6. Key occurs when a manual function is being requested from the Console. During Key, either all or part of the manual function is performed. The memory is not allowed to run during the Key cycle.
- 7. Keym occurs when the manual function requires a memory cycle, such as Examine or Program Load.
- 8. "Dummy" State occurs only when a machine stop is pending and the current instruction requires the skip conditions to be interrogated. During this state the machine increments the PC if the skip is successful in order that the address lights reflect the true next address.

#### TS Cycles

The TS cycles are four clock pulses long, and may be thought of as the time required to transfer a 16 bit word between two CPU registers at the rate of four bits per clock cycle. Each Major State consists of at least two complementary TS levels, called TS0 and TS3. TS0 occurs during the first half of the Major State, and TS3 occurs during the second half. Certain operations require more time than that provided by the two TS cycles, so a flip-flop called Loop is set to force the TS0 cycle to repeat and give the Major State three TS time intervals. During TS0 of this operation the data is fetched from the memory and loaded into the MBO; then Loop is set, TS0 is repeated, and the data in the MBO is shifted through the Adder. Finally, TS3 is set and the data is transferred from the MBO to the Memory and re-written.

#### **Timing Generator Cycles**

There are three timing generators, called the processor timing generator (PTG); the accumulator timing generator (ACTG) and the memory timing generator (MTG). These timing generators effectively designate the clock pulses for specific functions in the processor, accumulator and memory respectively.

The Processor Timing Generator. This two bit counter, designated, PTG0 and PTG1, cycles every four clock pulses. PTG0 is set during the two middle clock cycles of a TS cycle, and PTG1 is set during the last two cycles of a TS cycle. These two levels are decoded into two others called PTG2 and PTG5. PTG2 is the last clock interval during TS0, and PTG5 is the last clock interval during TS3. PTG5 is used, for example, to enable the major state flip-flops. PTG0 "anded" with TS0 to form PTG0. TS0, the first clock interval during TS0, is used to increment the Adder as the least significant four bit nibble is passed through it. Figures C-1 and C-2 show the timing for the PTG during FETCH or KEY major states. and all other states.

The Accumulator Timing Generator. This two bit counter, designated ACTG0 and ACTG1, is always one clock state ahead of the PTG counter. Its two signals are used to drive the accumulator chips. Their timing is given in Figure C-3.

The Memory Timing Generator. This four bit counter, designated MTG0, MTG2, MTG3, is used to form the control signals for memory. Its timing is given in Figure C-4.



NEXT MAJOR STATE

Figure C-1 Timing For The Processor Timing Generator During All Major States Except Fetch or Key

	NEXT MAJOR STATE
MEM 150 300 450 600 750 900 1050 1200 13 CLOCK (88-1-A6)	350 1
	Ļ
PTG0 (88-1-D4)	 +
PTG1 (88-1-D4)	<b>1</b>
TS0 (88-1-C5)	j-
TS3 (88-1-C5)	<b>_</b>
PTG= 0. TS0	j-
PTG=1·TS0	
PTG2 (88-1-D3)	
(88-1-D3)	
PTG= 1 · TS3	+
PTG5 ENAB	j-
END CYCLE	L
STUTTER (88-1-D7)	; ; <del>;</del>
DG-00044	NOTE: DATA IS ON BUS FOR $1050\mu$ sec.

Figure C-2 Timing For The Processor Timing Generator During Fetch or Key

BUS FOR  $1050\mu$  sec

MEM CLOCK (88-1-A6) ACTG0 (88-1-D8)	
ACTG1 (88-1-D8)	
TS0 KEY/FETCH	ſſ
TSO KEY/FETCH	<b>_</b>
TS3 KEY/FETCH	L
TS3 KEY/FETCH	L
END CYCLE KEY/FETCH	
END CYCLE KEY/FETCH	

DG-00046

ACCUMULATOR TRUTH TABLE (88-4-B6 & B7 U124 & U123)

ACTG0	ACTG	L
0	0	BITS 12-15
1	0	BITS 8-11
1	1	BITS 4-7
0	1	BITS 0-3

Figure C-3 Timing For The Accumulator Timing Generator





DG-00047

Figure C-4 Timing For The Memory Timing Generator

#### CPU DATA PATHS

#### Registers

The CPU is organized around eight hardware registers as shown in Figure C-5; a shift buffer (ACB); a program counter (PC); a CPU interface register (MBO); an instruction register (IR and MBC); and four accumulators, (AC0, AC1, AC2, AC3). These eight registers are all 16 bits long except for the PC which is 15 bits. All internal data paths are four bits wide, so it takes four separate operations to perform an add, or a register-to-register transfer.

<u>Program Counter (PC)</u>. The 15 bit address of the next instruction to be fetched is held in the PC. During the fetch of an instruction, the PC is incremented by one so that it points to the next sequential instruction. Certain instructions, such as JMP can change the contents of the PC. The PC consists of one 16 bit latch.

Instruction Register (IR and MBC). The Instruction Register stores the instruction currently being executed. The CPU decodes the data held in the Instruction Register in order to perform the instruction. The register is organized into two parts, the IR and MBC. The IR consists of the eight high order bits, and the MBC of the eight low order bits. During an effective address calculation, the MBC contains the displacement and shifts through the source multiplexer into the Adder and the IR bits remain static.

CPU Interface Register (MBO). The MBO is used in every operation the CPU performs. It acts as a parallel-to-serial converter for 16 bit data flowing into the machine from the MEM bus. This data is loaded from the MEM bus into the MBO in parallel, and shifted out four bits at a time into some other part of the machine. Conversely, data is shifted into the MBO from the Adder four bits at a time to be loaded into a Memory from the MBO bus. During effective address calculations, the MBO holds the present address used in relative addressing. During memory modify operations (such as ISZ) data is loaded into the MBO Memory. The MBO then modifies the data by recirculating it through the Adder and back into the MBO. The modified data is then loaded from the MBO back into Memory.

Shift Buffer (ACB). All data to be loaded into the Accumulators are passed through the ACB, where the results of an ALC instruction are assembled before they are loaded back into the Destination Accumulator.

Accumulators (AC0, AC1, AC2, AC3.) There are two identical sets of four - 16bit accumulators all of which can be logically and arithmetically manipulated under program control. Each set of accumulators is contained in a single 64 bit chip; (only one accumulator - nibble per chip can be addressed at any one time). Since it is necessary to be able to access two accumulators simultaneously, two sets are available, called source (S) and destination (D), each set containing the same information as the other. For example, two accumulators can be added together by simultaneously fetching the source data from one chip and the destination data from the other and then adding the two. The accumulators are buffered by four bit registers (source and destination) so that the next nibble can be selected while the current nibble is being processed. It takes 100 ns to access a nibble in the accumulator, and 100 ns to move a nibble through the Adder and Multiplexer, so by overlapping the two, the total time to process a nibble is 100 ns.

During the first nibble, the Adder is idle and a flag called STUTTER inhibits the clock until data is ready.

#### Data Flow

Nibble Transfers. When transferring data from one register to another, the lower order bits are always transferred first. The first clock interval would transfer bits 12-15, the second 8-11, the third 4-7, and the fourth 0-3. If an operation is to be performed upon a word, two things must be specified; the bit position inside the nibble, and the nibble to be acted upon. For example, to increment a word during FETCH. TS0 time when the MBO is incremented, a carry is inserted into the low order bit of the Adder during the first clock interval, PTG=0·TS0, so a "one" is added to that first nibble. If a carry resulted from that first addition, it is stored in a flip-flop for the next clock interval where it is inserted into the Adder as a carry into the low order bit. This continues until all four nibbles have passed through the Adder. During JSR it is necessary to force bit 0 to be zero as it is stored into AC3. A gate in the high order position of the nibble forces the output of the multiplexer/shifter gate high (to load zero) during JSR and the fourth clock interval during the time state in which the PC is being loaded into AC3.

Instruction Overlapping. Certain instructions are carried out at the same time as parts of other instructions. For example, any operation which loads an accumulator is overlapped with the next major state. Such is the case with the ALC instruction when the CPU first operates upon the accumulator(s), loads the result into the ACB register while memory is re-writing the instruction, and then waits until the next state to transfer the result from the ACB back into the accumulator. The next state could be FETCH, PI, DCH or even KEY. Another operation that is overlapped with the next Major State is the interrogation of skip conditions for ALC and ISZ/DSZ instructions. The results of these instructions are loaded into the ACB, which shifts through the multiplexer/shifter during TS0 of the next major state, after which the data may or may not be loaded into the accumulators. The output of the multiplexer/shifter is checked for all zeroes to see if it fulfills the skip conditions. If it does, the SKIP flip-flop is set at the end of TS0. If the next major state was FETCH, the execution of that instruction is inhibited, effectively skipping it, even though it was fetched from memory and loaded into the instruction register. If the next major state is PI, the PC that is loaded into address zero is incremented to reflect the skip before it is stored. If the next state is DCH and the SKIP flip-flop is left in the set state, appropriate action will be taken on the next FETCH or PI cycle. If the machine is about to be stopped from the Console by STOP, ISTP, or MSTP, a "Dummy State" is entered in which the skip conditions are interrogated, and the PC incremented as required to permit the ADDRESS lights on the Console to show the correct next address when the machine is stopped.

#### Data Buses

Data is transferred between memory and the central processor or an I/O device along three data buses called:

- **MEM** which transfers data from memory to the Central Processor;
- MBO which transfers data from the Central Processor to Memory;
- $\overrightarrow{\text{DATA}}$  which transfers data in either direction between memory and I/O devices.

During an output I/O instruction, data moves from the source AC into the MBO and on to the MBO bus. From the bus it is strobed into the memory MB register and on through the IN-OUT bus to the destination device. During an output I/O instruction the destination device outputs to the IN-OUT bus into the memory's MB register, which dumps into the MEM bus. The MEM bus is strobed into the MBO which moves it through the Adder to the ACB and into the destination AC.

#### THE FLOW AND TIMING DIAGRAMS

The following diagrams illustrate each step in the sequence of functions carried out by the central processor and memory. Each block of a flow diagram describes an operation, its data path and the location of critical logic. For example, this block means that the ACB register was transferred to an AC register via the  $ACB_{5}AC_{88-4-A7}$ 

shifter (ACB) which is located on print 001-000088, sheet 4, in grid A7. The symbol  $\Sigma$  means Adder, M means Multiplexer, and S means Shifter. Supporting notes near the blocks give the current time state, relevant figures and the status of important signals.

#### REFERENCES

1.	Nova 1200 CPU	Print D-001-000088-13
2.	Flow Charts	Print D-001-000106-00
3.	Waveforms	Print D-001-000107-00



Figure C-5 The Nova 1210 Central Processor




















































# Table C-1

# Adder and Multiplexer Control Signals During EFA Instructions

	*				*		
	S0	S1	S2	DISABLE D MULT	$\frac{EFA}{PTG1}$	$\frac{\overline{\text{ACD}}}{\text{OUT}}$	
REL · + (P6)	H/L	L	L	L	H/L	Н	
REL(P6)	H/H	L	L	L	H/L	Н	
(AC2) BASE +(AC3)	H/L	L	L	L	H/L	L	
(AC2) BASE -(AC3)	н/н	L	L	L	H/L	L	
PAGE ZERO	H/L	L	L	Н	H/L	H	DON'T CARE

*	H for	L for
FII	RST TWO	LAST TWO

NIBBLES NIBBLES

DG-00049

# Table C-2Adder Control Signals During ALC Instructions (TS3)

IR 5	BI? 6	rs 7	FUNCTION	IR5(1)=LOW DISABLE D MULT	ACD OUT	EFA PTG1	IR6(1) = HI S0	S1	IR6(0) = HI S2	IR7(1) = LOW  ADD  ONE
0	0	0	COMPLEMENT	Н	L	L	L	Н	н	Н
0	0	1	NEGATE	Н	L	L	L	Н	Н	L
0	1	0	MOVE	Н	L	L	Н	L	L	Н
0	1	1	INCREMENT	Н	L	L	Н	L	L	L
1	0	0	ADD COMPLEMENT	L	L	L	L	Н	H	Н
1	0	1	SUBTRACT	L	L	L	L	н	н	L
1	1	0	ADD	L	L	L	Н	L	L	Н
1	1	1	AND	L	L	L	Н	Н	L	L
A'	88- 7&1	2 6		88-2-B2	88-2 B2	88-2 A2	88-2 C2	88-2 C2	88-2 C2	88-2 D2

# Table C-3

# Carry Chart For ALC Instruction

PRIOR TO INSTRUCTION	IR 10	BITS 11	OVERFLOW OCCURRED?	CARRY AT COMPLETION
CARRY RESET	0	0	NO	RESET
CARRY RESET	0	0	YES	SET
CARRY SET	0	0	NO	SET
CARRY SET	0	0	YES	RESET
CARRY RESET	0	1	NO	RESET
CARRY RESET	0	1	YES	SET
CARRY SET	0	1	NO	RESET
CARRY SET	0	1	YES	SET
CARRY RESET	1	0	NO	SET
CARRY RESET	1	0	YES	RESET
CARRY SET	1	0	NO	SET
CARRY SET	1	0	YES	RESET
CARRY RESET	1	1	NO	SET
CARRY RESET	1	1	YES	RESET
CARRY SET	1	1	NO	RESET
CARRY SET	1	1	YES	SET

DG-00050



Memory Reference Instruction Decoding Chart

IR	[ 0	1	2	3	4		
1	0	0	0	0	0	JMP	SINGLE CYCLE(FETCH)
NO AC	0	0	0	0	1	JSR	$\int EXCEPT DEFER(BIT5=1)$
NC AC	0	0	0	1	0	ISZ	]
l	0	0	0	1	1	DSZ	TWO CYCLE(FETCH & EXEC)
10	0	0	1	AC	CD	LDA	EXCEPT DEFER(BIT5=1)
AC	lo	1	0	AC	CD	STA	J

# DATA CHANNEL SIGNALS

	REQENB	
	DCHR	
	DCHA	
	DATA BUS (0-15)	
	MODE (DCHM0-DCHM1)	
	DCHO	
	DCHI	
	OVERFLOW	
	DONE	
CPU	BUSY	INTERFACE
	INTR	

SEQUENCE:

- 1. REQENB TO I/O
- 2. DCHR TO CPU
- 3. DCHA TO I/O
- 4. a. MAIN MEMORY ADDRESS ON DATA BUS TO CPU
- b. MODE BITS TO CPU (SEE TABLE)
- 5. DATA ON DATA BUS DIRECTION DETERMINED BY TYPE OF OPERATION.
- 6. DCHO OR DCHI TO INTERFACE
- A. OVERFLOW LINE APPLIES ON TO INCREMENT MODE
- B. DONE, BUSY AND INTR SAME AS NORMAL I/O

# MODE BIT TABLE

DCHM0	DCHM1	FUNCTION
н	Н	OUT (WRITE)
Н	L	INCREMENT
L	Н	IN (READ)
L	L	NOT USED

DG-00031

Figure C-6 Data Channel Signals



Figure C-7 Deposit Timing Diagram



Figure C-8 Examine AC1 Timing Diagram



Figure C-9 ADD0, 1, SKP Timing Diagram



Figure C-10 MOV 0, 0 Timing Diagram



Figure C-11 Timing Diagram For Both The ISZ And DSZ Instructions



Figure C-12 LDA Timing Diagram



Figure C-13 STA Timing Diagram



Figure C-14 JMP @ 100 Timing Diagram



Figure C-15 JSR @ 20 Timing Diagram



Figure C-16 I/O Input Timing Diagram



Figure C-17 I/O Output Timing Diagram



Figure C-18 PI Timing Diagram



Figure C-19 Data Channel Increment Timing











Figure C-22 Data Channel Out Followed By Data Channel In Timing

# SECTION K

# THE OPERATOR'S CONSOLE

## INTRODUCTION

The console illustrated in Figure K-1, has a set of ADDRESS lights which display the contents of the MBO bus; a set of DATA lights which display the contents of the MEM bus; a register of toggle switches which will output to the MEM bus; a row of control switches at the bottom of the panel which instruct the computer on what to display in the lights, what to do with the information in the toggle switches, where to start or stop and how. The console also has a three position keyed rotary switch which turns power on and off and locks some of the operating switches.

## CONSOLE LIGHTS AND SWITCHES

All the lights in the console are continually drawing about 10ma each through series resistors, so their filaments are always hot (but not glowing) and large surge currents are avoided when the filaments are driven on.

### The Console ADDRESS Lights

These lights are always showing the state of the MBO bus which is driven directly from the MBO register. When the machine is running, the MBO register is continually shifting, so the display is meaningless; when the machine is stopped, the MBO register shows the contents of the PC, i.e., the next address.

## The Console DATA Lights

These lights are always showing the state of the MEM bus. When the machine is running this bus carries data from memory to the instruction and MBO registers; when the machine is stopped this bus contains the contents of the memory buffer of the last memory selected.

## The Console Operational Indicators

These lights are driven directly from their corresponding flip-flops in the central processor.



Issued by CPU

Figure K-1 The Console

The Console Switch Register

These switches connect non-inverting open collector buffers directly to the MEM bus. All drivers go low when the  $\overline{\text{CON DATA}}$  level goes low;  $\overline{\text{CON DATA}}$  is issued by the CPU during the READS instruction or during a console operation that requires input from these switches, such as EXAMINE.

# The Console Control Switches

All the control switches except STOP and RESET are wired through pull-up resistors to a common circuit which detects when current is flowing through a switch, initiates a delay to suppress contact bounce and then issues the signal  $\overrightarrow{\text{CON}}$  REQ to the CPU. This signal forces the CPU into the key sequence shown in Figure K-2 which returns the signal  $\overrightarrow{\text{CON}}$ INST to the console.  $\overrightarrow{\text{CON}}$  INST connects switches AC0, AC1, AC2, AC3, DEPOSIT, DEPOSIT NEXT, EXAMINE and EXAMINE NEXT through a decoder to the MEM < 0, 7> lines, which are input to the Instruction Register and interpreted as shown in Table K-1. The computer then goes into either the KEY or KEYM major state and follows the flows of Figure K-3.

The switches RESET, STOP, MEMORY STEP, IN-STRUCTION STEP and PROGRAM LOAD are wired separately to the CPU. RESET stops the computer at the end of the current cycle, issues the IORST pulse to all I/O devices, clears ION and sets the real time clock to the line frequency. STOP simply stops the computer at the end of the current instruction. MEMORY STEP takes the processor through the current state and then stops. INST STEP takes the processor through the current state and on to the end of the current instruction. Both signals force a  $\overline{\text{CON}}$  RQ to the CPU and output  $\overline{\text{MSTP}}$  and  $\overline{\text{ISTP}}$  respectively. PROGRAM LOAD deposits the contents of the bootstrap ROM into locations 0-37 and the machine at location 0. It outputs the signal  $\overline{\text{PL}}$  to the CPU.

The Console Rotary Switch

This switch controls the primary power to the power supply. It has three positions:

OFF	- the primary power is removed from the power supply
ON	- the primary power is applied to the power supply
LOCK	<ul> <li>the primary power is applied to the power supply but the STOP RESET</li> </ul>

## REFERENCES

switch is disabled

- 1. "How To Use The Nova Computers" 012-000089-00.
- 2. Nova 800/1200 Console Print D-001-000089-05.





KEY

RUN *DG-00037* 

Figure K-2 The CPU Key Sequence Timing Diagram

# Table K-1Control Switch Decoding To The Instruction Register

CONSOL	E									
INSTRUCTION		IR0	IR1	IR2	IR3	IR4	IR5	IR6	IR7	IR8 TO 15
	AC0	0	0	1	0	0	0	1	1	0
AC	AC1	0	0	1	0	1	0	1	1	0
DEP.	AC2	0	0	1	1	0	0	1	1	0
	AC3	0	0	1	1	1	0	1	1	0
	AC0	0	1	1	0	0	1	1	1	0
AC	AC1	0	1	1	0	1	1	1	1	0
EXAM.	AC2	0	1	1	1	0	1	1	1	0
	AC3	0	1	1	1	1	1	1	1	0
DEPOSIT		1	1	0	1	1	1	0	1	0
DEPOSIT NEX	Т	1	1	0	1	1	1	0	0	0
EXAMINE		1	1	1	1	1	0	0	1	0
EXAMINE NEX	ζT	1	1	1	1	1	1	0	0	0
MEMORY STE	Р	1	1	1	1	1	1	1	1	0
INSTRUCTION	STEP	1	1	1	1	1	1	1	1	0
PROGRAM LO	AD	1	1	1	1	1	1	0	1	0
START		1	1	1	1	1	0	1	1	0
WHEN GOES F 6-00036	BIT FALSE	ACD×.	ACD ACEA	Dr.D.	DEB. N	AC SE DX	D.F.R.C.F.	ALAN SALL	ALT ALT A	THE WAY AS A



Figure K-3 Key, KEYM And Manual Flow Diagrams
POA	······································	BACKPANEL	POA		BACKPANEL
PIN	SIGNAL	PIN	PIN	SIGNAL	PIN
1	GND	B1	27	+ 5	B4
2	MEM15	B18	28	MBO15	A41
3	MEM14	B76	29	MEM13	A35
4	MBO13	A37	30	MBO12	A39
5	MEM12	A36	31	MEM11	A51
6	MBO11	B5	32	MEM10	A45
7	MEM9	A53	33	+VIAMD	N/A (BUS TO
					POWER SUPPLY)
8	MBO9	B9	34	MEM8	A55
9	MBO7	B14	35	MBO6	B16
10	MEM6	B22	36	MEM5	B26
11	MBO5	B32	37	MEM4	B28
12	<u>MBO14</u>	A43	38	MBO3	B43
13	MEM2	B47	39	MEM0	B71
14	MBO1	B77	40	LAMP	GND
15	MBO2	B44	41	MEM1	B70
16	MBO4	B42	42	MEM7	B24
17	<u>GND</u>	B2	43	MEM3	B68
18	MBO8	B12	44	MBO10	B8
19	RESTART				
	ENABLE	A32	45	STOP	A31
20	RST	A30	46	CONT DATA	A28
21	CON RQ	A27	47	$\underline{\text{CONT}}_{+}\text{ISTP}_{+}$	
				MSTP	A25
22	$\underline{CON}$ INST	A22	48	MSTP	A20
23	<u>PL</u>	A19	49	CARRY	A15
24	ISTP	A17	50	FETCH	A13
25	ION	A16	51	EXEC	A11
26	RUN	A14	52	DEFER	A1Z

Table K-2 Backpanel Connections To The Console Through POA

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### SECTION P

### THE POWER SUPPLY

### INTRODUCTION

The Nova 1210 power supply is mounted on the backpanel below the circuit boards where it converts either 110Vac at 60Hz or 220Vac at 50Hz to regulated, current limited 5Vdc, -5Vdc, +15Vdc for the logic and memories, and to unregulated 6.3Vac for the real time clock. With the power monitor and restart option, the power supply interrupts the computer when it detects a line voltage failure (less than 90% of nominal), stops the computer when the voltage gets too low for reliable operation, and issues a start pulse to the computer when the line voltage recovers.

### POWER SUPPLY CIRCUITS

The 30V Unregulated Supply

110Vac or 220Vac are input through the power cord to a switch on the console S1, then on to transformer T1. The two primaries of T1 are wired in parallel for 110Vac, and in series for 220Vac. Note that the cooling fan operates on 110Vac only.

The secondary of the transformer is wired to a full wave bridge rectifier which outputs approximately + 30Vdc (30-35Vdc) into an RC filter, and subsequent-ly to the +5V and +15V series pass switching regulators.

The Series Pass Switching Regulators

A series pass switching regulator acts like a multivibrator which sets when it detects a low output voltage and resets when it detects a high output voltage. When the regulator is set, it gates current from the 30Vdc supply into an LC circuit and the load; when the regulator is reset, the load draws all of its power from the LC circuit until the circuit is sufficiently exhausted to be recharged by the regulator. The frequency at which the regulator sets and resets varies from 0 to 25KHz depending on the load.

There are two such regulators in the 1210 power supply, one for the +15Vdc (Figure P.1) and the other for the +5Vdc (Figure P.2). The -5Vdc is taken from a 3:1 transformer in the +15Vdc circuit.

Note that the outputs of these circuits are DC levels with about .15V ripple at frequencies which vary with the loads.

The Fuses

The 1210 power supply has two 10A fuses, one between the power cord and the switch S1, and the other just after the bridge rectifier. The first will blow if there is a short in the cabling to S1, the second will blow if the  $\pm 15$ Vdc or  $\pm 5$ Vdc levels rise high enough to trigger an SCR, which then creates a short between the 30V supply and ground.

The Power Fail Module

This module detects a line voltage failure and outputs the signals shown in Table P-2.

#### **REFERENCES:**

- 1. Fairchild Semiconductor Integrated Circuit Data Catalog - Fairchild Semiconductor 1970
- Backpanel Nova 1210 print No. D-001-000207-00
- Backpanel 1210 Power Supply print No. D-001-000172-02

### Table P-1

Output Voltage Level Name	Output Voltage	Maximum Current	Used On	Remarks
+ V Lamp	14.5→15.1Vdc (.15V ripple)	88	Console Lamps	Full Wave Rectified, short circuit & over- voltage protection; regulated
+ V MEM	**	)	XY Drivers	** **
-5V	-5→-7Vdc (.15V ripple)	1A	Sense Amplifiers	Overcurrent Protected by a diode
+ 5V	5.2-5.4VDC (.15V ripple)	10A	IC Logic	Full Wave Rectified, short circuit and overvoltage protection regulated
RINH<0, 15>	14.5→15.1Vdc (.15V ripple)	760mAdc each	Inhibit Drivers	<b>11 11</b>
60Hz	6.3Vac	500mAdc	Real Time Clock	This signal has the same frequency as the line (input) voltage
B84	14.5-15.1Vdc (.15V ripple)	3Adc	Memory Drivers	Turns off memory drivers when +15Vdc reaches +12Vdc
A10(VINH)	14.5→15.1Vdc (.15V ripple)	J	Memory Inhibit Logic	Current Limited

## Output Voltages of the Nova 1210 Power Supply

Table P-2

## Output Signals of the Nova 1210 Power Fail Module

SIGNAL NAME	SIGNAL FUNCTION
PWR FAIL	-sets the POWER LOW flag in the processor when the line voltage drops to 90% of nominal voltage.
MEM OK	-resets the RUN flag and stops the computer when the +Vmem (+Vdc) voltage goes too low for the memory to function reliably.
+ 5 OK	sets the RUN flag and starts the computer when the $+5Vdc$ has risen to 4.4Vdc.





Figure P-1 Simplified Schematic of the  $\pm$ 5Vdc Series Switching Regulator. When the comparator senses a difference between the (divided) reference voltage (1) and the output voltage (2) it switches, turning on the driver transistor (3) and consequently the series pass transistors (4). Current is shunted through the series pass transistors to the coil, output capacitor and load (5). The output voltage rises, reducing the error voltage to the comparator, which resets, turning off the driver (3) and consequently the series pass transistors. Now the load is supplied from power stored in the LC circuit. The back emf developed across the coil as a result of this switching is dropped across the free wheeling diode (6). Note that each time the comparator is forced to switch it is driven into saturation by the positive feedback loop which includes the 220K resistors (7).

The current limiter (8) turns on if the output voltage drops below about 4V, turning the driver (3) and subsequently the series pass transistors (4) off. The supply is latched in this state until power is removed and then returned.

The diode at (9) feeds the 15V into the +5V supply during power down, forcing the 15V to drop faster but the +5V to the IC's to hold longer. The memory driver supply is switched at (9) of Figure P-2, when the 15V drops too low.



Figure P-2 Simplified Schematic of the +15Vdc Series Switching Regulator and the -5V Supply. When the comparator senses a difference between the reference voltage (1) and the divided output voltage (2), it switches, turning on the driver transistor (3) and consequently the series pass transistors (4). Current is shunted through the series pass transistors to the coil, output capacitor and load (5). The output voltage rises, reducing the error voltage to the comparator, which resets, turning off the driver (3) and consequently the series pass transistors. Now the load is supplied from power stored in the LC circuit. The back emf developed across the coil as a result of this switching is dropped across the free wheeling diode (6). Note that each time the comparator is forced to switch it is driven into saturation by the positive feedback loop which includes the 220K resistor (7).

The current limiter (8) turns on if the output voltage V MEM drops too low, or if the current at either terminal of (9) (memory inhibit and memory drive) is too high. When on, the current limiter turns off the driver and subsequently the series pass transistors, latching the supply into this mode until power is removed and then returned.

The transistor at (9) will switch off when the +15V drops too low for memory to function properly, thus removing power to the memory drivers.

The -5V is generated through the 3:1 transformer at (10). The  $50\Omega$  resistor at (11) guarantees -5V (i.e., voltage across the coil) during No Load.

### SECTION M

### THE MEMORY

#### A REVIEW OF CORE MEMORIES

A "bit" of information can be stored in a ferrite core by magnetizing the core in one of two possible directions or "states" and then calling one state a "1" and the other state a "0", similar to a flip-flop. Unlike a flip-flop, however, a core cannot be read simply by examining its output voltages; a core is read by forcing it into the "0" state and then watching for the current pulse which is always generated when a core changes state. If the pulse occurs, then the core must have been in the "1" state before it was excited; if no pulse occurs then the core must already have been in the "0" state because no transition took place.

Reading a core, then, always leaves it in the "0" state and although the information that it contained has probably been transferred to some register which was set by the current pulse, that information is no longer in the core, and it usually has to be restored with what is called a "write cycle". Writing means setting the core to a one or a zero, depending on the state of the memory register that usually contains core bound information.

Reading or writing into a core is a matter of sending current pulses along wires into the core; the direction of current relative to the core determines into which state the core will move. Data General's core memories contain many thousands of these ferrite cores strung together like beads on wire. Each core has three wires passing through it, and these wires carry the currents to magnetize them and the pulses which occur when they change state. The memories are wired so that the computer can select any group of 16 bits at once, and read or write a complete 16 bit word "in parallel". A group of 16 cores, called an "address" is picked by passing current down two selected wires called X and Y, which are strung into the cores so that they both pass through only one address. The combined effect of current in these two wires is enough to flip the core into the zero state if it is not already there. Each core that flips sends a pulse down its own third wire called the sense wire which is then fed into one flip-flop of a 16 bit Memory Buffer. The flip-flop sets if it sees a pulse, and remains static if it does not. The register which selects the X Y wire or "lines" is called the Address Register.

Restoring the contents of the address involves resetting those core bits that set ones into the Memory Buffer. This is done by sending reverse currents down all the X and Y lines of that address, and inhibit currents to these bits which should remain in the "0" state. The contents of the memory buffer could be changed before this write-cycle so that new information is entered into the address.



Figure M-1 Simplified Schematic of a Memory Core

A core will remain in the "one" state until currents pass through the X and Y excitation windings and force it into the "zero" state. The transition causes a pulse to travel down the sense winding to the detection logic. The core can be reset to the "one" state by reversing the currents in the X and Y windings. The transition will still cause a pulse to be generated in the sense and inhibit winding, but the sense logic is disabled at this point.

### DATA GENERAL'S CORE MEMORIES

The memories used on the basic computer consist of cores arranged in a three wire 3D scheme in which the sense and inhibit functions share the same wire. The cores are laid out in a single plane in mats, and wired together in the bow tie pattern shown in Figure M-2. There are four core planes available; 1K, 2K, 4K, and 8K. Each plane is assembled on a "daughter" board which is mounted on a 15" by 15" "mother" board, where most of the memory logic sits. Power is supplied by the chassis supply.

The memory logic on any board consists of drivers, sense amplifiers, a Memory Address Register, a Memory Buffer Register, Multiplexers, and Memory select logic shown in Figure M-3.

Data is transferred between memory and the central processor or an I/O device along three data buses called:

- **MEM** which transfers data from memory to the Central Processor;
- MBO which transfers data from the Central Processor to Memory
- DATA which transfers data between memory and I/O devices in either direction.

### The Memory Select Logic

When a memory board is plugged into a computer, its select logic must be wired to respond to the correct code in the MA register, since the MA registers of all boards are loaded with the same address at the same time. This wiring is done with a set of jumpers that connect either the 0 or 1 side of the high order MA bits to an "and" gate. The output of this "and" gate will be true only if the code for which it is wired is in the MA register, and only when this output is true can the memory respond. This code must be unique to that memory board.

The jumpers are forced into points on the board. These points are located on the logic side of the board at the lower right hand corner when its fingers are pointing at you. If there is a mixture of boards, i.e., 1K, 2K, 4K or 8K, it is a good policy to wire the largest board for low core, the second largest above it and so on. This way there will not be any gaps in the system's core map.

Figures M-4 and M-5 show how the select logic of the four types of boards are jumpered.

#### **REFERENCES:**

8K	Memory Prints	#001-000238-00
4K	Memory Prints	#001-000236-00
2K	Memory Prints	#001-000234-00
1K	Memory Prints	#001-000232-00



Figure M-2 Simplified Schematic of The Core Memories Sense and Inhibit Lines

The sense and inhibit functions share the same wire. The sense circuitry, (1), sees both ends of the wire, and detects negative pulses with a differential amplifier. The output of this amplifier is examined at STROBE time.

The inhibit logic, (2), drives +15Vdc level into the middle of the same wire at INHIBIT time. The current is divided and passes through all cores to ground through the diodes at the other end.



\* Issued by CPU

### Figure M-3 Core Memory

During a typical FETCH instruction, the CPU outputs the memory address on the MBO <0, 15> data lines and then issues MA LOAD. READ I/O is high, so the address is strobed into the Memory Address register and output to the driver select logic. Then, READ 1 and READ 2 are issued, gating the X and Y currents to the selected address. A little later, STROBE is output by the CPU and it gates all core pulses into their corresponding Memory Buffer bits. The Memory Buffer is then re-read back into core by reversing all the driver currents and gating the INHIBIT signal issued by the CPU to those bits which are not to be reset. If the contents of the address are to change, the Memory Buffer is loaded with the new word before the address is re-written.



1K BOARDS						
MA BITS JUMPERED		)	BOARD NUMBER	ADDRESSES ENABLED (OC TAL)		
1	2	3	4	5		
0	0	0	0	0	1	00000-01777
0	0	0	0	1	2	02000-03777
0	0	0	1	0	3	04000-05777
0	0	0	I	Т	4	06000-07777
0	0	Ι	0	0	5	10000-11777
0	0	Т	0	Т	6	12000-13777
0	0	I	1	0	7	14000-15777
0	0	Т	I	Т	8	16000-17777



Selecting 1K Memory Boards. On the lower right hand side of the board between U33 and U34 there are 3 sets of 5 points. The first two sets are wired to MA < 1, 5 > on the 1 and 0 side respectively; the last set of points is wired to the "and" gate. The board of this figure is wired for 00001, board #2.



2K BOARDS						
MA BITS JUMPERED			TS RED		BOARD NUMBER	ADDRESSES ENABLED (OCTAL)
I	2	3	4			
0	0	0	0		1	00000 - 03777
0	0	0	Ι		2	04000 - 07777
0	0	Ι	0		3	10000-13777
0	0	Ι	Т		4	14000 - 17777
0	1	0	0		5	20000 - 23777
0	1	0	Ι		6	24000 - 27777
0	1	1	0		7	30000 - 33777
0	ł	1	1		8	34000 - 37777
20.	000	05 1				



Selecting 2K Memory Boards. On the lower right hand side of the board between U33 and U34 there are 3 sets of 4 points. The first two sets are wired to MA <1, 4> on the 0 and 1 side of each flip-flop; the last four points are wired to the "and" gate. The board of this figure is wired for 0000, board #1.

### Figure M-4 Wiring Up The Select Logic of 1K and 2K Boards



	4K BOARDS					
MA BITS BOARD ADDRESSES ENA JUMPERED NUMBER (OCTAL)						ADDRESSES ENABLED (OCTAL)
I	2	3				
0	0	0			I	00000-07777
0	0	I			2	10000-17777
0	I	0			3	20000-27777
0	1	Т			4	30000-37777
1	0	0			5	40000-47777
Ι	0	1			6	50000-57777
I	1	0			7	60000-67777
I	T	1			8	70000-77777



Selecting 4K Memory Boards. On the lower right hand side of the board between U33 and U34 there are 3 sets of 4 points. The first two sets are wired to MA < 1, 3> on the 1 and 0 sides respectively, the last set is wired to the "and" gate. The board of this figure is wired for 010, board #3. ONLY THE FIRST THREE POINTS OF A SET SHOULD BE JUMPERED.



**8K BOARDS** MA BITS BOARD ADDRESSES ENABLED (OC TAL) JUMPERED NUMBER 2 I. 0 0 T 00000 - 17777 0 I. 2 20000 - 37777 0 T 3 40000 - 57777 60000 - 77777 1 I. 4 DG-000958



Selecting 8K Memory Boards. On the lower right hand side of the board between U30 and U31 there are 2 sets of 6 points. The first set is wired to MA <1, 3> on the 1 and 0 sides; the second set is wired to the "and" gate. The board of this figure is wired for 10, board #3. ONLY THE FIRST FOUR POINTS OF EACH SET SHOULD BE JUMPERED.

Figure M-5 Wiring Up The Select Logic of 4K and 8K Boards

### Table M-1

SIGNAL NAME	FUNCTION
DATA <0, 15>	16 bidirectional lines which carry information to and from devices on the IN-OUT bus.
DRIVE I/O	Issued by CPU-1 to strobe the MB register onto DATA $<0$ , 15> lines.
INH TRAN	Issued by CPU-1 to prevent the MB register from outputting to the MEM $<0$ , 15> bus during a data transfer from the console.
INHIBIT SELECT	Issued by CPU-1 to prevent the memory from being selected.
MA LOAD	Issued by CPU-1 to load the MA register.
MEM <0, 15>	16 lines which carry information from the memory to CPU-1.
MB CLEAR	Issued by CPU-1 to clear the MB register.
MB LOAD	Issued by CPU-1 to load the MB register.
READ 1	Issued by CPU-1 to select the memory drivers.
READ 2	Issued by CPU-1 to select memory drivers.
READ I/O	Issued by CPU-1 to enable the DATA $<0$ , 15> lines into the MD $<1-15>$ lines.
RELOAD DISABLE	Issued by CPU-1 to inhibit MB Load.
STROBE	Issued by CPU-1 to strobe core pulses into the Memory Buffer.
MBO <0, 15>	16 lines which carry information from CPU-1 to memory.

### External Memory Signals

### SECTION I

### INSTALLING THE COMPUTER

#### INTRODUCTION

This section explains how to unpack, assemble and cable the computer.

### PLACING THE COMPUTER

The computer room must be large enough to accommodate the equipment, operating personnel, tables and chairs, storage space (for tapes, manand listings), service clearances and possible future expansion. The room should be well lit and clean, with adequate primary power. The temperature and humidity must fall within acceptable tolerances of the most sensitive peripheral.

Overhead sprinklers should be "dry pipe" systems that remove primary power from the room and turn on a battery operated light source before opening the master valve. If power connections are made under the floor, use waterproof receptacles and connections. Any carpeting should be of the type that minimizes static electricity, and metal flooring should be well grounded.

### UNPACKING THE COMPUTER

The computer is shipped in the kit shown in Figure I-1.

- 1. Open the top of the outer carton; remove all cables, manuals, packing filler, etc.
- 2. Remove the styrofoam container (it and contents weigh about 50 pounds) and place it on a flat surface right side up.
- 3. Unstrap the container and remove the top.
- 4. Carefully remove the styrofoam block from the back of the computer.
- 5. Remove the computer, placing your hands under the chassis front and back.
- 6. The computer is sometimes shipped with cardboard spacers in spare slots to keep the boards from vibrating during shipment. Remove these.

### Table I-1

### The Nova 1210 Electrical, Mechanical and Environmental Specifications

Voltage (AC)	Current (A) NOMINAL @ 115V	Power Dissipation (W)	Heat Dissipation (Btu/hr)	Operating Temperature (min-max F)	Stora <b>ge</b> Temperature (min-max F)	Humidity (Rel) (min-max)	Maximum Wet Buib	Maximum Cable Length	Dimensions (inches)	Service Clearance (inches)	Weight (1bs)
110	9	1000	3400	32-130	-30- +160	20% 90%	78 <sup>o</sup> F	IN-OUT 50FT	HEIGHT 5¼" WIDTH 17½" LENGTH 22¼"	BACK 3" FRONT 36"	PACKED 55 UN- PACKED 40

The Nova 1210 operates from a single phase source at 115V 60Hz or 220V  $\pm$ 50Hz all  $\pm$ 20%. This device has a separate 4.5 foot power cord terminating in a standard 3 wire single phase male connector. An earth ground connection must be supplied through the power cord.



Figure I-1 The Nova 1210 Shipping Kit

### PACKING THE COMPUTER

#### 1. Locate the original shipping container and packing material. If it is not available, order a shipping kit from Data General Corporation. DO NOT SHIP THE COMPUTER IN ANY OTHER CONTAINER.

- 2. Fill any spare slots inside the chassis with just enough cardboard spacers so the boards don't bounce during shipment.
- 3. Place the computer in the bottom half of styrofoam container "front justified" with the back end on top of the extra rib. Pack the power cord into the hollow area at the back. Fill in the space at the back with the styrofoam block to prevent the computer from moving during shipment.
- 4. Put on the top of the styrofoam container and strap the two pieces together.
- 5. Put the styrofoam container into the cardboard box. Place any odds and ends on top of the container, and fill in any empty spaces with cardboard or pieces of styrofoam.
- 6. Close and seal the cardboard box.
- 7. Call your local Field Service representative for the correct address if the equipment is to be shipped to Data General Corporation.

Assembling the computer outside the factory involves installing memory or controller boards or mounting the chassis into a 19" rack.

ASSEMBLING THE COMPUTER

Installing or Removing Boards

The Nova 1210 computer, has slots for four  $15'' \times 15''$  circuit boards which plug into four sets of 100 pin connectors on the PC backpanel (Figure I-2). The slots are numbered from the bottom up and assigned as follows:

Slot Number	Boards Accepted
1	CPU-1 Only
2	Any 1210 Memory or the Multiply Divide option (8107)
3	Any 1210 Memory or the I/O Interface As- sembly (4007)
4	Any 1210 Memory or Controller

Note that slot 3 has special wiring for the 4007.



DG-00098

Figure I-2 Nova 1210 Board Slots



Figure I-3 Rack Mounting Hardware For The Nova 1210

Note that if the Multiply Divide option 8107 is used, it must go into slot 2, and if the I/O Interface Assembly is used it must go into slot 3. If a new memory board is installed, check that the select logic jumpers are correct (see section M).

If boards are installed or removed from the computer chassis it is important that the integrity of the Program Interrupt and Data Channel priority systems be preserved. The Priority systems of the Program Interrupt and Data Channel facilities each use a scheme in which a wire is chained through every controller one after the other in such a way that only when there is an enabling level on that wire can a controller effectively request service of the facility. The enabling level on the wire will appear at any given controller only if all controllers closer to the computer on the chain are not requesting service themselves; i.e., whenever a controller requests service it removes the enabling level from all devices below it on the chain. There are two chains, one for the Program Interrupt and the other for the Data Channel.

The program interrupt chain enters a board slot at pin A96 and leaves at pin A95; the data channel chain enters at pin A94 and leaves at pin A93. (See "How to Use the Nova Computers" for more details.)

Here are the rules:

- 1. Memories do not use the daisy chain systems so the chains bypass them.
- 2. All controllers that use the interrupt system must be included in the interrupt chain; all controllers that use the data channel must be included in the data chain.
- 3. The Data Channel and Program Interrupt chains are completely independent and must not cross. Each chain must run through the controllers in series, NEVER in parallel.
- 4. Be careful of controllers that use the Program Interrupt system but do not use the Data Channel system; the Data Channel chain must bypass them.

Rack Mounting The Computer

The Nova 1210 can be mounted in a standard 19 inch rack, so each unit is shipped with rack slides attached and all of the necessary mounting hardware included. Figure I-3 shows how the right side of the rack slide is assembled in a cabinet; the other side uses identical hardware.

Leave at least two inches open at the back for cables and about 36" open at the front for servicing. The console protrudes 1 3/4" inches out of the front of the rack.

### CABLING ASSEMBLIES TOGETHER

### Types of Cables

There are five types of cables used on a typical installation; I/O cables, device cables, internal cables, interdevice cables, and adapter cables. The correct cables are supplied with the equipment unless otherwise specified in the price list.

<u>I/O Cables</u> connect peripheral controllers mounted outside the computer chassis, to the computer IN-OUT bus. The cables form a daisy chain from controller to controller and finally to the computer chassis, where the first cable must terminate in a female connector compatible with the 100 finger male called P3 shown in Figure I-4. Controllers mounted inside the chassis are connected to the IN-OUT bus through backpanel etching, and therefore do not need an I/O cable.

Device Cables connect each peripheral controller to the device it is controlling. When such a controller is inserted into the Nova 1210 chassis, an internal cable is run from the appropriate backpanel pins to a male connector such as P5 of Figure I-4. The device cable must then run between the male paddle board on the 1210 chassis and the device.

Internal Cables are added when the controller is added, whether in the factory or in the field, so each shipment includes a wire list for the internal cable, and the internal cable itself. Figure I-4 shows how the paddle boards are mounted on the chassis.

Interdevice Cables interconnect peripheral devices. Some controllers will drive more than one device of the same kind, such as industry compatible tape controllers. In this case the device cables are daisy chained from device to device in the same way that the I/O cables are chained between controllers. The cables which interconnect the devices are not always the same as the device cable that runs from the controller to the first device, however, so these cables are called "interdevice cables".

Adapter Cables reconcile different cabling schemes. The Nova, Supernova, Nova 1200 and Nova 800 series computers use Cannon connectors instead of paddle boards for their device and I/O cables, and Data General supplies adapters so that peripherals used on these machines can also be used on the new models, or the other way around.



Figure I-4 -Sketch of the Nova 1210 Cabling Scheme

Signals from the backpanel pins are connected to edge connectors called P3, P4 and P5 which are mounted parallel to the backpanel at the back of the chassis. The fingers of P3 are permanently connected to the IN-OUT Bus signals according to Table I-2, via etched tracks on the backpanel's PC board. P4, a three plug 60 finger paddle board is mounted and wired-in only when the paper tape reader, the paper tape punch or the EAI options are installed in slot 3. P5, a 100 finger paddle board which accepts 48 signal wires and 2 ground wires is mounted on standoffs beside P4 and wire wrapped to backpanel pins when it is needed. P2, the teletypewriter cable is mounted on the backpanel pins A-83, 85, 87, 89, 97, 99, keyed to 3B69, 3A6. POA is an edge connector through which backpanel signals communicate with the console.



### Table I-2

	P3	
LETTER SIDE	NUMBER SIDE	SIGNAL NAME
	1 THRU 50	GND
A		$-$ GND
В		PWR ON (+5V)
$\overline{\mathbf{c}}$		MSKO
D		INTA
Ē		DATIB
F		$-$ DATIA
Ĥ		DS3
Ţ		DATOC
ĸ		CLB
T.		STRT
й М — — — —		
N		DATO B
D		
r D		DCHA
S		DCIIA DS4
5 T		D54 D55
I		
U V		
V XV		LODST
vv v		
Y		
Z		SELD
a		SELB
D		
c		INTP OUT
d		DCHM0
e		DCHMI
I		INTR
n		DCHU
j		DCHR
<u>k</u> — — — –		DCHI
1		DOFLO
m		RQENB
n		
р		DATA14
r		$ \frac{\text{DATA15}}{\text{DATA11}}$
s		DATAII
t		DATAIZ
u		DATA8
v		DATA4
w — — — –	•	$ \frac{\text{DATA0}}{\text{DATA0}}$
х		DATA9
У		
Z		DATAI
AA		DATA15
AB — — — –	<u>+</u>	DATA3
AC		DATA10
AD		
AE		DATAG
AF		GND

#### P3 Interconnections for Nova 1210

#### Cabling The System

### REFERENCES

Turn all systems off, do not plug in any power cords, then:

- 1. install all internal cables not factory installed,following the instructions in the appropriate controller's manual.
- 2. install all device cables remembering not to exceed the maximum length in each case. Be careful to protect each cable from wear and tear.
- 3. install the teletypewriter cable as shown in Figure I-4.
- 4. measure the line voltage of each service outlet, and check that it is correct for the computer.
- 5. measure the voltage between the ac return line and the frame ground at each outlet. THIS MUST BE ZERO.
- 6. plug the power cord of each device into its service outlet.

Nova 1210 Rack Installation Print D-010-000013-01.

How To Use The Nova Computers -012-000001-01.

### SECTION N

### MAINTAINING THE COMPUTER

### INTRODUCTION

The Data General Corporation supports its equipment with a large field service organization, customer training programs and technical documentation. This section summarizes these services and includes tips on preventive maintenance, recommended tools and trouble shooting.

### FIELD SERVICE ORGANIZATION

### Field Service Programs

Data General's Field Service Organization currently offers its users a choice of three maintenance services. These services are subject to change without notice.

- 1. On Call Service Contract under which DGC will repair equipment at the installation when DGC is notified of a problem by the user. DGC also provides preventive maintenance on a regular schedule under this contract. Parts, labor and travel are included in the monthly payment schedule which is determined by the type and amount of equipment to be serviced and the distance between the installation and the nearest DGC service center.
- 2. Warranty Extension Service Contract under which DGC will:
  - repair equipment when it is returned to the DGC factory in Southboro, Mass. The user assumes full responsibility for freight and insurance charges to and from the plant. Parts and labor are included in the monthly payment schedule.
  - (2) repair equipment at the installation when notified of a problem by the user. Parts are included in the monthly maintenance schedule, labor is charged at reduced rates and travel is charged at the prevailing standard rates.
- 3. <u>Hourly Service</u> under which parts, labor and travel are charged as needed at prevailing rates. No contract is signed for this service.

Field Service will also generate on request a complete spare parts list for any installation, and rent or sell replacement and loaner boards.

General Terms and Conditions (Subject to change without notice).

- 1. Equipment which is not under a DGC service contract or normal warranty is subject to an inspection by DGC Field Service before it is eligible for a service contract. All costs for this inspection are borne by the user.
- 2. The user must bear all maintenance costs incurred as a result of unauthorized changes to DGC equipment. These costs will be charged as <u>Hourly Service</u>, regardless of the type of service contract existing between DGC and the user.
- 3. No additional service charge will be added for new (add-on) equipment until the warranty period of that equipment has expired.
- 4. All services are offered between 9 a.m. and 5 p.m. Monday through Friday excluding DGC holidays.
- 5. The minimum contract period is 6 months.
- 6. Field Service price schedules are available on request from Data General Field Service, Southboro, Mass. 01772, Telephone 617-485-9100.

### TRAINING ORGANIZATION

Data General's Training Organization currently offers its users four types of training courses. These courses are subject to change without notice.

Mainframe Maintenance Course. This course covers the logical structure of the central processor, memory, operator's console and power supply. Students must have experience with digital logic, integrated circuits and computer principles.

Fundamentals of Mini-Computer Programming. This course covers number systems, logic, flow charts and computer architecture. Students should have an aptitude for mathematics.

Basic Programming. This course covers Data General's assembly language utility software including loaders, editors, debuggers and assemblers. Students should have experience in programming.

Advanced Programming. This course covers Data General's Operating Systems, DOS, RTOS and SOS. Students must have experience in programming.

Courses are scheduled regularly in the training department at Southboro, Mass., and occasionally in field offices. Special courses can be arranged.

For more information call or write

Training Department Data General Corporation Southboro, Mass. 01772

Tel. 617-485-9100

#### PREVENTIVE MAINTENANCE

Periodically carry out the checks listed in Table, N-1, and remember the following points:

- 1. it is very poor practice to use the equipment as a counter top, particularly for liquids like coffee or soft drinks.
- 2. always check the line voltage before plugging an expensive piece of equipment into an unknown socket. (see Section I).
- 3. be careful not to get metal filings into the equipment; for example never let the equipment room be cleaned with steel wool.
- 4. never clean the equipment with a vacuum cleaner that has a metal (conducting) noz-zle.
- 5. always be aware that too much heat, moisture or contaminants can do much to harm the equipment. (see Section I).
- 6. be very careful how cables are routed; they should never be strained, cramped or crushed (underfoot).

Preventive 1	Preventive Maintenance Check List					
Item	Check					
Mechanical Connections	<ol> <li>that all screws are tight and that all mechanical assem- blies are secure.</li> </ol>					
	2. that all crimped lugs are secure and properly inserted onto their mating connectors.					
Wiring and Cables	<ol> <li>all wiring and cables for breaks, cuts, frayed leads, or missing lugs.</li> </ol>					
	2. wire wraps for broken or missing pins.					
	3. that no wires or cables are strained or cramped.					
	<ol> <li>that cables do not interfere with doors, and that they do not chafe when doors are opened and closed.</li> </ol>					
Air Filters	all air filters for cleanliness and for normal air movement through cabinets.					
Modules and Components	<ol> <li>that all modules are properly seated. Look for areas of dis- coloration on all exposed surfaces.</li> </ol>					
	2. all exposed capacitors for signs of discoloration, leakage, or corrosion.					
	3. power supply capacitors for bulges.					
Indicators and Switches	all indicators and switches for tightness; check for cracks, discoloration, or other visual defects.					
Fans	for broken fan blades.					
Diagnostics	Run all diagnostics periodically					

Table N-1

	Recommended Maintenance Tool Kit										
ITEM	QTY	DESCRIPTION	MFG. & PART No.								
1	1	6" combination slip joint pliers	Utica # 5-6								
2	2	5 $1/2$ " needle nose pliers	Utica # 654-5 1/2								
3	1	4" needle nose pliers	Utica # 23-4								
4	1	5" diagonal wire cutters	Utica # 44-5								
5	1	4" diagonal wire cutters	Utica # 347-4 CFJS								
6	1	5" ignition pliers	Utica # 517-5								
7	1	Screwdriver kit including handle, 3/16", 1/4", 5/16" slotted #1, #2 phillips blades, each 4" long	Xcelite # 99 PV-6								
8	1	3/32 slotter screwdriver with 2" blade	Xcelite # R3322								
9	1	1/8" #0 phillips screwdriver	Xcelite # P12S								
10	1	Magnetic pick up tool	Bonney # K26								
11	1	3/32 through 3/8, 10 pc nut driver set	Xcelite # PS120								
12	1	Xacto knife									
13	· 1	6" adjustable wrench	Utica # 91-6								
14	1	Ignition wrench	Bonney # N24R								
15	1	Set of 25 feeler gauges with 3" blades	Bonney # K53								
16	1	Set of 15 hex keys	Bonney # N6R								
17	1	Slotter 5" screw starter	Bonney # 5527								
18	1	Phillips 6 1/4" screw starter	Bonney # 556								
19	1	5" adjustable wire strippers	Utica # 110-5								
20	1	Set of 4 cut needle files	Hunter # F228A								
21	1	4 1/2" electrical tweezers	Hunter # B3M3								
22	1	flash light									
23	1	Can Quick Freez (circuit cooler)									

Table N-2

### Table N-2

ITEM	QTY	DESCRIPTION	MFG. & PART No.
24	1	Can degreaser (flex remover)	
25	2	16P I/C test clip	
26	1	23 $1/2$ watt soldering iron with iron plated chisel tip	Ungar
27	1	47 1/2 watt soldering iron element	
28	1	11b, 60/40 resin core solder	Kester
29	3	Spools of solder wick	
30	2	Acid brushes	
31	1	Vacuum solder removal tool	
32	1	Multimeter	Simpson # 260
33	1	Tool carrying case	
34	1	Oscilloscope	Tektronics # 453
35	1	Current probes	Tektronics # P60-22

### Recommended Maintenance Tool Kit (Continued)

## Table N-3

### The Nova 1210 Diagnostics

Diagnostic	Part No.	Binary Tape No.	Description
Address Test	097-000007	095-000005	checks memory address selection logic
Checkerboard III	097-000014	095-000031	tests memory sense amplifiers and inhibit logic
Nova 1210 Logic Test	097-000017	095-000036	tests CPU logic other than I/O
Nova 1210 Instruction Timer	097-000019	095-000038	tests CPU clock logic and outputs time-to-complete for each instruction
Exerciser	097-000004	095-000012	tests CPU logic, teletypewriter, reader, punch and real-time clock;
Arithmetic Test	097-000018	095-000037	exercises arithmetic and logical instructions in CPU

#### HOW TO TEST THE COMPUTER



- 13. Depress DEPOSIT NEXT several times and check that the PC increments
- 14. Depress EXAMINE NEXT several times and check that the PC increments





|--|

### Table 1 - Nova 1210/1220

0	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
ACB0 ACB1 ACB2	105 106 107	5 5 5	88-4	B4 B3 A4	ACB12 ACB13 ACB14 LOAD MBO*	105 106 107 98	14 14 14 6	88-4 '' 88-3	B3 B2 A4 A3
ACB3 ACB4 ACB5 ACB6 ACB7 ACB8 ACB9 ACB10	108 105 106 107 108 105 106	5 7 7 7 9 9	77 17 17 17 17 17 17	A3 B4 B3 A4 A3 B4 B3	KEYM SET* ACB15 ACB0 ACB1 ACB2 ACB3 ACB4 ACB5 ACB5	101 108 105 106 107 108 105 106	9 14 3 3 3 2 2 2	88-1 88-4 '' '' '' ''	B7 A2 B4 B3 A4 A3 B4 B3
ACB10 ACB11	107	9	**	A4 A3	ACB6 CRY SET ACB7 SHIFTER Logic	107 81 108 114	2 13 2 10	88-3 88-4	A4 C6 A3 A8
ACB12*	105	11 12	••	B4 B3	ACBIZ SAVE SHIFTER Logic SHIFTER	69 109 125	3 9 19	88-1 88-4 ''	D5 A8 A7
ACB13 ACB13* ACB14	106 106 107	11 $12$ $11$	17	В2 '' А4	SHIFTER SHIFTER	125 125	2 20	,, ,,	A7 A7
ACB14*	107	12	"	A3	SHIFTER SHIFTER SHIFTER	125 125 125	1 5 18	** ** **	A7 A6 A7
ACB15 ACB15* ACB12 SAVE	108 108 69	11 12 5	"' " 88_1	A2 A2 D4	SHIFTER	125	3	,,	Α7
AC CLR	20	9	"	A6	Logic IR(SH) SHIFTER LOAD AC*	90 83 125 111	1 5 7 3	88-4 88-2 88-4 88-3	A7 B8 A8 D3
ACD0 ACD1 *Indicates ''Not''	123 123	5 7	88-4	B8 B8	MULT D BUFFR MULT	120 122 120	5 3 2	88-4 ''	D5 C8 D5

r										
0	RIGIN	_			DES	TINA	TION	· ·		
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
					D BUFFER	122	2	88-4	C8	
ACD2	123	9	88-4	B8	MULT	120	22	**	C5	
					D BUFFER	122	15	''	C7	
ACD3	123	11	**	B8	MULT	120	19	**	C5	
					D BUFFER	122	14	**	C7	
ACD3 SEL*	50	6	88-2	D4	ACD	123	1	11	B8	
ACD4 SEL*	44	8	**	C4	ACD	123	15	**	B8	
ACD OUT*	45	6		B3	D MULT(SEL)	121	1	**	C8	
	124	5	88-4	B7	S BUFFER	115	3		C7	
	124	1		B7		115	2		C7	
	124	9		BO		115	15		C6	
[ACS3]	124		00 0	B6		115	14		C6	
ACSI SEL*	49	0,0	88-2	C4	ACS	124			B7	
	49	э, <u>п</u>	00 1	B4	ACS	124	15	00 1	B7	
ACIGU	54	9	00-1	D0		13	9	88-1		
					IR(SH) LUGIC	111		88-2	B8	
					ACD	120	14	00-4	B8 D7	
	54	77	00 1	D0	ACS	124	14	00 1		
ACIGI	54	1	00-1	D0		111	9	00-1		
						111	9	00-2		
					ACS	120	13		D0 B7	
A DDEB0	117	13	88-4	דת	CRV SET*	81	3	88-3		
ADDIMO	111	10		<i>D</i> .	ACB(DS)	105	4	88-4	R4	
					ACB8	105	15		B4	
					PC LOGIC	118	5 4	••	B6	
					MULT	120	4	,,	D5	
ADDER1	117	11	88-4	D7	ACB(DS)	106	4	••	B3	
					ACB9	106	15	••	B3	
					PC LOGIC	118	1.2	**	B6	
					MULT	120	1	••	D5	
ADDER2	117	10	88-4	D7	ACB(DS)	107	4	••	A4	
					ACB10	107	15	••	B2	
					PC LOGIC	118	12.			
							13	••	A6	
					MULT	120	23	**	C5	
ADDER3	117	9	88-4	D7	ACB(DS)	108	4	''	A3	
					ACB11	108	15	''	A2	
Indicates ''Not''										

Table 1 - Nova 1210/1220

T1-2

## Table 1 - Nova 1210/1220

OF	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
ADD ONE* ADDER TEST ALC ALC*	88 58 94 50	8 3 6 8	88-2 88-3 88-2 88-2	D2 A4 B7 B7	PC LOGIC MULT ADDER LOOP SET* DISABLE D MULT S0 TEST SKIP SET ADD ONE* AND	118 120 117 104 46 47 86 44 65	9, 10 20 7 5 10 1 5 2 5	88-4  88-3 88-2  88-3 88-2 	A6 C5 D6 D6 B3 C3 D8 D3 B7
ALC· <del>SKIP</del> AND AND ENAB*	83 65 64	10 6 11	88 - 3 88 - 2 88 - 2	D8 B7 B7	AND E SET S2 ALC S BUFFER (SH) LOAD CRY* CRY ENAB S1 ADDER IO DCDR AND PACK	65 74 91 94 115 97 91 117 62 65 89	5 12 5 13 13 2 5 8 13 4 2	" " 88-3 " 88-2 88-4 88-4 88-1 88-2 88-3	B7 C7 C3 B7 C7 C5 C6 C3 D8 A5 B7 C5
CARRY (F/F) CARRY* (F/F) CLK FLOP	76 76 20	8 9 5	88-3 '' 88-1	C5 C5 A6	CRY ENAB CON IND (A15, P49) CRY ENAB MA LOAD* CPU CLK MEM CLK LOAD AC*	77 6 77 56 72 73 93	4 5 3 10 2, 12 3 5	88 -3 89 -1 88 -3 88 -1 '' 88 -3	C7 C8 C7 D3 A7 A7 D3
*Indicates ''Not''					LOAD AC*	93	5	88-3	D3

## Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION				
SIGNAL	СНІ₽	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRII
CLK FLOP*	20	6	88-1	A7	CLK FLOP	20	2	88-1	A7
[CLR*]	63	5	**	A4	CLR	7	1	11	A4
CLR	7	2	**	A4	(IO CLR PLS)	(A50)		90-1	1
CLR ION*	63	11	**	B4	ION	84	4	88-2	C7
CLR SKIP*	99	8	88-3	В3	SKIP	79	13	88-3	B5
					LOAD MBO*	98	10	**	B3
[CON0*](S11)	6	4	89-1	C8	MEM0*	(B71)	(391)	89-1	C8
	1				(CON IND)	7	9	**	C8
[ CON1*](S12)	6	2	89-1	C7	MEM1*	(B70)	P41	**	C7
					(CON IND)	7	13	**	C7
[CON2*](S13)	6	8	89-1	C7	MEM2*	(B47)	(P13	) ''	C7
				~	(CON IND)	7	3	**	C7
[CON3*](S14)	6	12	89-1	C7	MEM3*	(B68)	(P43		C7
				<b>G A</b>	(CON IND)	7	1	**	C7
[ CON4* ] (S15)	3	8	89-1	C6	MEM4*	(B28)	(P37		C6
		10		<u>.</u>	(CON IND)	8	13	**	
[CON5*](S16)	3	10	89-1	Co	MEM5*	(B26)	(P36		
		~	00.1	CG	(CON IND)	8	3		
$[\text{CON6}^{\dagger}](\text{S17})$	ა	0	89-1			(B22)			
[ CONT7*](C10)	2	4	00 1	C5	(CON IND)	0 (D94)	1 (D49		
[CON (* ](S10)	3	4	09-1	05	(CON IND)	(D24) 0	12		$C_{5}$
[CON9*](S10)	2	2	80_1	C5	(CON IND) MEM8*	9 (A55)	13 D34	.,	C5
	5	4	09-1	00	(CON IND)	(HJJ) Q	2	·,	C5
[CON9*](S20)	3	12	89-1	C5	MEM9*	(A53)	(P7)	,,	Č5
	Ŭ	14	00-1	Ũů	(CON IND)	9	1	••	C5
[CON10*](S21)	4	8	89-1	C4	MEM10*	(A45)	(P32	,,	C4
	Ť	Ŭ	00 1	-	(CON IND)	10	13	,,	C4
[CON11*](S22)	4	10	89-1	C4	MEM11*	(A51)	(P31	**	C4
					(CON IND)	10	3	**	C4
[CON12*](S23)	4	12	89-1	C3	MEM12*	(A36)	(P5)	11	C3
[001112 ](021)	-				(CON IND)	10	1	**	C3
[CON13*](S24)	4	6	89-1	C3	MEM13*	(A35)	(P29	) ''	C3
					(CON IND)	11	13	**	C3
Indicates ''Not''									

OI	RIGIN				DESTINATION				
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[CON14*](S25)	4	4	89-1	C3	MEM14*	(B76)	(P3)	89-1	C3
	<b>I</b> .				(CON IND)	11	3	**	C3
[CON15*](S26)	4	2	89-1	C2	MEM15*	(B18)	(P2)		C2
	4	8	88-1	Δ2	(CON IND)	12 (A99)	$13 \\ D46$		C2
CONDAIN	Ĩ		00-1	A4	[CON0*](S11)	(A20) 6	3	,,	C8
					[CON1*](S12)	6	1	••	C7
					CON2* (S13)	6	9	**	C7
					[ CON3* (S14)	6	13	**	C7
					[ CON4*](S15)	3	9	11	C6
					[CON5*](S16)	3	11	11	C6
					[CON6*](S17)	3	5	11	C6
					$[CON(^{*})(S18)]$	3	3	,,	C5
					$[CON0^{+}](S19)$	ວ ຊ	1 1 2	**	
					[CON10*]	5	10		$C_4$
					(S21)	4	9	**	C4
					[CON11*]		-		
					(S22)	4	11	11	C4
					[ CON12* ]				
					(S23)	4	13	11	C3
					$\begin{bmatrix} \text{CON13*} \end{bmatrix}$		_		~ ~
					(S24)	4	5	**	C3
					$\begin{bmatrix} \text{CON14}^{+} \end{bmatrix}$	4	2	,,	
					(S23) [CON15*]	т	3		$C_2$
					(S26)	4	1	**	02
CON INST*	36	8	88-1	A2	()	(A22)	P22		
					[CON INST]	5	9	**	A8
[ CON INST ]	5	8	89-1		MEM0*	1	2	**	C8
-					MEM1*	1	4	**	C7
					MEM2*	2	10	**	C7
					MEM3*	1	12		C7
					NEN4* MEM5*	1	10	,,	
					MEM6*	$\frac{4}{2}$	14	,,	
					MEM7*	$\frac{2}{2}$	4	,,	C5
*Indicates ''Not''		ĺ				Ĩ	-		00

SIGNAL LIST Table 1 - Nova 1210/1220

0	RIGIN				DESTINATION					
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
CON RQ*	5	6	89-1	C8		1				
	(A27)	(P21	P		KEY SEEN	3	4	88-1	B8	
MSTP*	(A20)		89-1	в3	KEY ENAB*	3	2	88-1	<b>B</b> 8	
CPU CLK	72	6,8	88-1	Ā6	MB LOAD	14	4	"	C2	
					IR4-IR7	28	6	88-2	A6	
					MBC	32	6		A4	
					MBC	33	6 6	00 1	A5 C4	
	J				MBO	38	6	11	$C_{3}$	
					MBO	39	6	11	D3	
	ł				MBO	40	6	**	D4	
						42	6	88-1	C8	
					LOAD PC*	57	10	88-3	B3	
				]	MA LOAD*	60	10	88-1	$D^2$	
					PTG	69	6		D4	
					SKIP	78	13	88-3	B5	
					MAJOR					
					STATES	95	6	88-2	D6	
					CARRY F/F	0.7	•	00 0		
					Logic	97 102	9	88-3		
					LOOP/PACK	102	0			
					/EFA	103	6	11	D5	
					ACB	105	6	88-4	B4	
					ACB	106	6	**	B3	
					ACB	107	6		A4	
					ACB	108	D		АЗ	
					F/F	113	13	88-1	D5	
CPU INST	6	11	88-2	B7	INTA	6	5	11	B5	
					IORST	6	10	"	A4	
					(SKIP Logic)	11	2	88-3	B7	
						11	12		B7	
					(Reads)	24	4	88-1	A3	
*Indicates ''Not''										

# SIGNAL LIST Table 1 - Nova 1210/1220

## Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION				
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
CPU INST*	10	6	88-2	В7	(IO OCDR) HALT* PACK Logic MSKO*	64 71 87 4	2 2 4 13	88-1 88-2 88-3 88-1	B5 C8 C6 A4
CRY ENAB	80	11	88-3	C6	CPU INST CRY SET* CRY ENAB	6 81	12, 13 4	88-2 88-3	B7 C6
CRY ENAB SAVE	102	9	88-3	D7	SAVE SHIFT Logic	102 90 114	15 10 13	'' 88-4	D7 A7 A8
CRY OUT*	117	16	88-4	D8	SERIAL CRY CRY ENAB	54 91	14 1	88-1 88-3	D7 C6
CRY SET*	81	8	88-3	C5	CRY SET SAVE CARRY F/F	42 76	15 12	88-1 88-3	C7 C5
CRY SET SAVE	42	9	88-1	C7	(SKIP Logic)	77	9	**	B7
DATA0*	16 17 (P62)	11 1	103-1	C	Terminator			88 - 3	C8
DATA1*	(B02) 16 17 (D05)	8 3	103-1 ''	С	Terminator			88 - 3	C8
DATA2*	(B65) 14 15	11 1	103-1	С	Terminator			88 - 3	C8
DATA3*	(B82) 14 15 (D <b>7</b> 2)	8 3	103-1 ''	С	Terminator			88 - 3	C8
DATA4*	(B73) 12 13 (B61)	11 1	103-1 ''	С	Terminator			88-3	C8
*Indicates ''Not''									

SIGNAL	LIST

## Table 1 - Nova 1210/1220

ORIGIN					DESTINATION					
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
DATA5*	12 13	8 3	103-1	С	Terminator	Ι		88-3	C8	
DATA6*	(B57) 10 11	11 1	103-1 .,	С	Terminator			88-3	C8	
DATA7*	(B95) 10 11	8 3	,, ,,	С	Terminator			88-3	C8	
DATA8*	(B55) 8 9	11 1	103-1 ''	С	Terminator			88-3	C8	
DATA9*	(B60) 8 9	8 3	103-1 ''	с	Terminator			88-3	В8	
DATA10*	(B63) 6 7	11 1	103-1	с	Terminator			88-3	B8	
DATA11*	(B75) 6 7	8 3	103-1 	с	Terminator			88-3	B8	
DATA12*	(B58) 4 5	11 1	103-1	С	Terminator			88-3	B8	
DATA13*	(B59) 4 5	8 3	103-1 ''	с	Terminator			88-3	B8	
DATA14*	(B64) 2 3	11 1	103-1 ''	с	Terminator			88-3	B8	
DATA15*	(B56) 2 3	8 3	103-1	с	Terminator			88-3	B8	
[DATOA*] DATOA DATOB*	(B66) 25 7 25	6 8 5	88-1 ''	B4 B4 B4	DATOA DATOB	7 (A58) 7	9 13	88-1 90-1 88-1	В4 В4	
DATOB *Indicates ''Not''	7	12	88-1	В4	MSKO*	4 (A56)	12	 90-1	В4	
OI	RIGIN				DESTINATION					
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SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
[DATOC*] DATOC [DATIA*]	25 26 25	4 6 0	88-1	B4 B4 B4	DATOC	26 (A48)	5 12	88-1 90-1	B4	
DATIA	25 5	, 12	"	B4 B4	CON DATA*	24 (A44)	5	00-1	A3	
[DATIB*] DATIB	25 5	10 10	**	B4 B4	DATIB INTA	5 6 (A42)	11 4	88-1	В4 А4	
[DATIC*] DATIC	25 7	11 6	**	B4 B4	DATIC IORST	7 6 (454)	5 9	88-1 ''	В4 А4	
[D BUFFR0] [D BUFF1] [D BUFFR2] [D BUFFR3]	122 122 122 122 122	5 7 9 11	88-4 '' ''	C8 C8 C8 C8 C8	[ D MULT0] [ D MULT1 ] [ D MULT2 ] [ D MULT3]	121 121 121 121 121	2 5 14 11	88-4 ''	C8 C8 C8 C8 C8	
DCH	23	9	88-1	C6	DCHI DCH LOOP ENAB	14 15	9 2	88-1 88-1	C2 B3	
DCHA	69	7	88-1	D4	DCHA* DRIVE IO* DCH	$\begin{array}{c} 41\\7\\13\\23\end{array}$	2 11 5 15	88-2 88-1 ''	D4 C2 B3 C6	
DCHA* DCHA SET*	7 71	10 8	88-2 88-1	C2 C4	[DCHA SET] FETCH	(A60) 67 97	3 1	90-1 88-1 88-2	C4 D7	
[DCHA SET] DCHI	67 14	4 8	88-1 ''	C4 C2	DCHA DRIVE IO*	69 (B37) 13	2 4	88-1 90-1 88-1	C4 B3	
DCH LOOP ENAB	15	6	88-1	В2	OVFLO DCHO	15 18	9 12.	88-1	B2	
					ACTG(LD)	75 104	13 10 10	88-1 ''	B2 D8	
						101	13	88-3	C6	
*Indicates ''Not''										

<u>Table 1 - Nova 1210/1220</u>

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#### SIGNAL LIST

<u>Table 1 - Nova 1210/1220</u>

O	RIGIN				DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
DCHM0* [DCHM0] DCHM1*	(B17) 16 (B21)	2	88-1 88-1 ''	B3 B3 B3	DCH LOOP ENAB [DCHM0] DCHI " [DCHM1]	15 16 14 14 16	4,5 1 10 12 3	88-1 '' ''	B3 B3 B2 B2 B3
[ DCHM1 ] DCHO DCHR* DCHR PEND	16 18 (B35) 13	4 8 3	88-1 '' ''	B3 B2 C5 C5	LOOP SET* OVFLO DCHR PEND DCHA SET*	34 15 (B33) 13 71	12 10 2 10	88-3 88-1 90-1 88-1	C6 B2 C5 C5
DEFER	95	7	88-2	D6	DEFER AGAIN ADD ONE* DEFER* LOOP SET*	104 76 90 94 104	9 4 4 11 6	88-3 88-3	D6 C7 D4 D6 D6
DEFER*	94	10	88-2	D6	(CON IND) S0 ADDER TEST ADDER	(A12) 48 58	(P52 1 12	89-1 88-2 88-3	D0 C2 C4 A6
DEFER AGAIN*	76	5	88-2	C7	TEST FETCH + DEFER D SET	59 75 74	10 2 9	" 88-2 "	A6 C7 C7
(D+ESET) + TS3	36 06	11		D5	DCHR PEND (RUN LOGIC) PC IN*	13 24 35	1 13 1	88-1  88-2	C5 B7 D5
D+E SET*	90	11	88-2	DΊ	(D+ E SET)+ TS3 (RUN LOGIC) FETCH LOGIC	36 43 97	13 13 5	88-2 88-1 88-2	D5 B7 C7
*Indicates ''Not''									

SIGNAL	LIST	
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Table	1	-	Nova	1210	/1220	

0	ORIGIN					DESTINATION			
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
Disable D Mult DIV* [D MULT0] [D MULT1] [D MULT2] [D MULT3]	53 (A91) 121 121 121 121	3 4 7 12 9	88-4 '' ''	B2 C5 C7 C7 C7 C7 C7	D Mult (Enab) Carry F/F ADDER '' ''	121 76 117 117 117 117	15 10 19 21 23 2	88-4 88-3 88-4 ''	C8 C5 D7 D7 D7 D7
DRIVE IO*	12	8	88-1	B2	READ IO* [DRIVE IO]	(B88) 12 18	4,5 1	90-1 88-1 103-1	В2 С8
[DRIVE IO]	18	2	103-1	C8	[Drive IO Select]	26	9, 10, 12	103-1	C8
[DRIVE IO· Select]	26	8	103-1	C8	DATA0* DATA1* DATA2* DATA3* DATA4* DATA5* DATA6* DATA6* DATA7* DATA8* DATA9* DATA10* DATA11* DATA12* DATA13* DATA15*	$     \begin{array}{r}       16 \\       16 \\       14 \\       12 \\       12 \\       10 \\       10 \\       8 \\       8 \\       6 \\       4 \\       4 \\       2 \\       2     \end{array} $	12 10 12 10 12 10 12 10 12 10 12 10 12 10 12 10 12 10	······································	ς ουοοοοοοοοοοοοοο
*Indicates ''Not''									

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SIGNAL LIST	
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Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION				
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
DS0* DS1* DS2* DS3* DS4* DS5*	8 8 22 8 8	8 10 12 8 4 2	88-1 '' '' ''	C4 C4 C4 C4 C4 C4 C4		(A72) (A68) (A66) (A46) (A62) (A64)		90-1 '' '' ''	
D SET	74	8	88-2	C6	DEFER E SET D+E SET*	95 96 96	2 2 13	88-2 	C6 C6 D7
DSZ'E'IS0+ EFA	32 103	11	88-2 88-3	D5	SU MBC(SH) MBC(SH) ACD4 SEL* ACD OUT* Disable D Mult S0 S0 D SET	92 32 33 44 45 46 47 47 47	1 13 13 9 10 4 3 4	88-2 '' '' '' ''	C3 A5 A4 C5 B3 B3 C3 B3 C3 C7
EFA*	103	12	88-3	D5	JSR · EFA EFA · PTG1 ACD4 SEL* ACD3 SEL*	93 34 44 50	13 5 1 3	** ** **	C8 A3 C5 C5
$EFA \cdot \overline{PTG1}$	34	6 1	88-2	A2	MBC (DS) S Mult (SEL)	32 116 53	4 1 10	,, 88-4	A4 C7
	110	1	00-1	00	End Cycle(F/F) LOAD CRY* (LD) Test Skip (LD) Loop/ Pack Shifter Logic '' ''	113 97 102 103 109 114	10, 12 2 12 10 10 13 1	88-1  88-3  88-4 	C8 C5 D8 D5 A8 A8
*Indicates ''Not''									

SIGNAL LIS	Т
	والانتخاذ والمحاد

O	RIGIN				DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
End Cycle*(F/F)	113	6	88-1	C5	Shifter Logic PTG0·TS0	114	9	88-4	A8
E SET	96	3	88-2	C6	Logic EXEC D+ E SET*	112 95 96	15 12	88-1 88-2 ''	A6 D6 D7
EXEC	95	9	88-2	D6	EXEC* (INST DCDR)	73	11	**	D6 B5
EXEC*	73	10	••	D6	(CON IND) (INST DCDR)	(A11) 52	(P51 15	89-1 88-2	C1 B5
EXT LOAD*	(A47) (B49)			A3 A8	LOAD AC* Shifter (Enab)	111 125	4 8 9	88-3 88-4	D3
EXT Select*	(B80)			110	SELECT	35	9, 9, 10	103-1	AU
FETCH	95	5	88-2	D6	MB LOAD LOAD IR LOAD PC* FETCH·TS0* ALC* ION FETCH* CLP SYLD*	13 34 61 64 50 85 94	13 9 10 9 9 1 13	88-1 88-2 88-3 88-2 '' ''	C3 A7 B4 D5 B8 C6 D6
FETCH*	94	12	88-2	D6	(CON IND) ACD OUT*	(A13) 45	4 (P50 1, 13	)89-1 88-2	В4 С2 В4
Fetch+ Defer	75	3	88-2	C7	FETCH+ DEFER ADD ONE* IR0+ SKP	75 89 50	1 12 1	77 77 77	C7 D3 B6
FFTCH.TS0*	64	8	88-2	D4	E SET EFA	74 85	$13 \\ 12$	7.7 7.7	C7 C5
Ferrer Lord ID*	(195)	Ŭ	00 <u>1</u> 00 1	A 9	Mult (SEL)	120	16	88-4	C5
*Indicates ''Not''	(A09)		00-2	AO	тқ(цц))	14	4	00-2	AO

O	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
HALT*	71	6	88-2	C7	MB LOAD (RUN LOGIC) DCHA	14 62 71	2 3 9	88-1 ''	C2 B7 C5
INH0	34	9	103-1	в		16 16	1	103-1	C
INH0* INH1	34 34	8 5	103-1 ''	B B	(INHB0) (Q15) MEM1* DATA1*	68 16	12 5 9	103-2 103-1	7 C C
INH1* INH2	34 32	6 5	103-1 ''	B B	(INHB1) (Q16) MEM2* DATA2*	68 14 14	2 1 13	103-2 103-1	7 C C
INH2* INH3	32 32	6 9	103-1 ''	B B	(INHB2) (Q13) MEM3* DATA3*	64 14 14	259	103-2 103-1	7 C C
INH3* INH4	32 31	8 9	103-1 ''	B B	INHB3) (Q14) MEM4* DATA4*	64 12 12	12 1 13	103-2 103-1	0 7 C C
INH4* INH5	31 31	8 5	**	B B	(INHB4) (Q11) MEM5* DATA5*	58 12 12	12 5 9	103-2 103-1	7 C C
INH5* INH6	31 28	6 5	103-1 ''	B B	(INHB5) (Q12) MEM6*	58 10	2 1 13	103-2 103-1	7 C C
INH6* INH7	28 28	6 9	103-1 ''	B B	(INHB6) (Q9) MEM7* DATA7*	55 10	2 5 9	103-2 103-1 	7 C
INH7* INH8	28 27	8 9	103-1 "	B B	(INHB7) (Q10) MEM8* DATA8*	55 8 8	12 1 13	103-2 103-1	0 7 C C
INH8* INH9	27 27	8 5	103-1 ''	B B	(INHB8) (Q7) MEM9* DATA9*	48 8 8	12 5 9	103-2 103-1	4 C C
INH9* INH10	27 24	6 5	103-1 ''	B B	(INHB9) (Q8) MEM10* DATA10*	48 6 6	2 1 13	103-2 103-1	4 C C
INH10*	24	6	103-1	В	(INHB10)(Q5)	45	2	103-2	4
*Indicates ''Not''									

O	RIGIN				DESTINATION				
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
INH11	24	9	103-1	В	MEM11*	6	5	103-1	С
INH11* INH12	24 23	8 9	103-1 ''	B B	DATA11* (INHB11) (Q6) MEM12*	6 45 4	9 12 1	'' 103-2 103-1	C 5 C
INH12* INH13	23 23	8 5	** **	B B	DATA12* (INHB12) (Q3) MEM13* DATA13*	4 39 4 4	13 12 5 9	103-2 103-1	5 C C
INH13* INH14	23 21	6 5	103-1 ''	B B	(INHB13) (Q4) MEM14* DATA14*	39 2 2	2 1 13	103-2 103-1 ''	5 C C
INH14* INH15	21 21	6 9	103-1 103-1	B B	(INHB14) (Q1) MEM15* DATA15*	37 2 2	2 5 9	103-2 103-1 ''	5 C C
INH15* INHB0 INHB1	21 70 70	8 3 5	103-1 103-2 ''	В 7 7	(INHB15) (Q2) Q15 Q16	37	12	103-2	5 7 7
INHB2 INHB3 INHB4	63 63 61	3 5 3	** ** **	7 7 7	Q13 Q14 Q11				7 7 7
INHB5 INHB6 INHB7	61 53 53	5 3 5	** ** **	7 7 7	Q12 Q9 Q10				7 7 7
INHB8 INHB9 INHB10	51 51 43	3 5 3	11 11 11	4 4 4	Q7 Q8 Q5				7 4 4
INHB11 INHB12 INHB13	43 42 42	5 3 5	** **	4 4 4	Q6 Q3 Q4				4 4 4
INHB14 INHB15	20 20	3 5	11 11	4 4	Q1 Q2				4 4
*Indicates ''Not''									

SIGNAL	LIST	

O	RIGIN				DESTINATION				
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
INH GATE B	26	6	103-1	D2	(INHB8) (Q7) (INHB9) (Q8) (INHB10) (Q5) (INHB11) (Q6) (INHB12) (Q3) (INHB13) (Q4) (INHB14) (Q1) (INHB15) (Q2)	48 48 45 45 39 39 37	13 1 13 13 1 1 1	103-2 '' '' '' '' ''	4 4 4 4 4 4 4 4 4
INHIBIT	13	8	88-1	C2	INH GATE A, B WRITE MEM	(B30) 41 41	13 9 2	103-1 103-1 ''	D3 D3 D3 D3
SELECT* INPUT*(F/F)	(B85) 66	8	103-1 88-1	D8 B5	SELECT DRIVE IO* (IO INST DCDR)	35 12 25	5 10 15	103-1 88-1	D8 B3 B4
[ INTA* ] INTA INTR* INH TRANS*	6 5 (B29) 56	6 8 6	88-1 '' 88-1	A4 A4 B2	MB LOAD INTA PI SET [INH TRANS•	112 5 (A40) 75 (B45)	1,9 9 12	90-1 88-2 90-1	C3 A4 C7
INH TRANS.					SEL	36	2,5, 4	103-1	C8
SEL]	36	6	103-1	C8	MEM0* MEM1* MEM2* MEM3* MEM4* MEM5* MEM6* MEM7* MEM8* MEM9* MEM10* MEM11* MEM12*	$ \begin{array}{c} 16\\ 16\\ 14\\ 14\\ 12\\ 12\\ 10\\ 10\\ 8\\ 8\\ 6\\ 6\\ 4\\ \end{array} $	2 4 2 4 2 4 2 4 2 4 2 4 2 4 2 4 2 4 2 4	103-1 	000000000000000000000000000000000000000

OI	RIGIN		<u>.</u>		DES	TINA	ΓΙΟΝ	[	
SIGNAL	СНІ₽	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
IO• E	42	5	88-1	C8	MEM13* MEM14* MEM15* IO·E* (IO Inst DCDR) (IO DCDR) HALT* LOOD SET*	4 2 94 64 62 71	4 2 4 3 4 2 1	103-1  88-1  88-2 88-2	C C C7 D5 A5 C8
IO· E* [IO(F+D*] IO(F+D)	94 51 27	4 12 6	88-1 88-2 ''	C7 B6 B5	(Pack Logic) MA LOAD* IO(F+D) INPUT F/F Logic	80 89 60 27 9	9 4 13 5 12 3	88-3 88-3 88-1 88-2 88-1	C5 D2 B6 C5 C5
ION	82	6	**	C7	(SKIP Logic)	42	13	88-3	B7
ION*	84	6	88-2	C7	ION* (CON IND) ION (ION LOGIC)	84 (A16) 82 85	5 (P26 5 5	88-2 ) 89-1 88-2 ''	C7 D2 C7 C7
[IO PLS*] IO PLS IORST IO SKIP*	63 26 10 25	4 4 8 12	88-1 '' ''	A7 A4 A4 B4	IO PLS	26 (A74) (A70) 26	3	88-1 90-1 90-1 88-1	A4 B4
IO SKIP IR0*	26 28	2 5	88 -1 88 -2	B4 A6	SKIP INC* (Skip Logic) (RUN LOGIC) ACD OUT* SH/SWP DCDR '' PC ENAB* (Pack Logic)	87 59 43 45 50 51 53 92	1     5     10     3     13     1     4,5     4	'' 88-3 88-1 88-2 88-2 '' 88-3 88-3	B8 B6 B7 B3 B6 B6 B4 C6
IR5·IR6 IR0+SKIP	65 50	3 12	88-2 88-2	В8 В6	AND ENAB* HALT* ALC* (SH/SWP DCDR)	64 71 50 51	12 4 11 15	88-2 '' ''	B8 D8 B8 D6
*Indicates ''Not''									

O]	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
ISTP* (ISZ+DSZ)E	(A17) 84	(P24 8	89-1 88-3	B8 D6	(RUN LOGIC) CRY SET*	24 81	9 9, 10	88-1 88-3	В7 С6
(ISZ+DSZ)E*	52	9	88-2	В4	LOOP SET* (INST DCDR) (ISZ+DSZ)E Togt Skip Set	104 52 84	2 1 13	88-2 88-3	D6 B5 D6
ISZ·E·TS0*	52	5	88-2	B4	ADD ONE*	89 89	1 9	88-2	D8 D3
(JMP+JSE) (F+D) JSR.EFA	48 92	11 11	'' 88-3	В5 С3	PC ENAB* JSR·EFA* SHIFT ACB	61 93 100	3 2 1	88-3 88-2 88-3	B4 C7 C3
JSR·EFA*	93	12	88-2	C7	WAS JSR JSR·EFA (Dack Logic)	103 92	3 13 2	17 17	D5 C3
КЕҮ	23	5	88-1	C6	(Pack Logic) KEY* LOAD IR CON INST* (RUN LOGIC) KEYM SET* Disable D Mult	99 6 34 36 43 55 46	2 1 10 9 5 5	88-1 88-2 88-1  88-2	C5 C7 A7 A2 B7 B6 B3
КЕҮ*	6	3	88-1	C6	LOAD PC* KEY·LOOP (DS) ADD ONE* INH TRANS* MA LOAD* (Pack Logic) LOOP SET* CLR SKIP*	61 23 44 56 56 70 84 99	5 2 4 5 4 9 13 10	88-3 88-1  88-2 88-1  88-3 	B4 C6 D3 B2 D3 C6 C6 B3
KEY ENAB*	3	3	88-1	B8	PRESET*	3	12 2	88-1	B7 C7
KEY·LOOP	4	3	88-1	C6	CON DATA* ACD OUT* LOAD MBO*	4 45 98	10 2 13	'' 88-2 88-3	A2 A3 B3
*Indicates ''Not''									

O	RIGIN				DESTINATION				
			DIVG	CDID		CITID		DWG	
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DwG	GRID
KEYM	23	11	88-1	Сb	(DUN LOCIC)	24	კ ი	88-1	A3
					(RUN LOGIC)	43	4	00 0	B7
KEVM*	23	12	88_1	CG	ADD ONE	41	1	00-2	$D^4$
KEYM. PL	41	8	88-1	C5	KEYM SET*	55	3	88_1	B6
		Ŭ		<u> </u>	KEYM PL TSO	57	$\frac{1}{2}$	88-3	C4
					JSR · EFA	93	9	11	C4
					LOAD MBO*	98	5	**	A3
KEYM · PL ·									
TS0*	57	3	88-3	C3	INH TRANS*	56	5	88-1	B2
					LOAD PC*	57	4	88-3	B3
KEYM SET*	55	6	88-1	B6	[KEY M SET]	22	1	88-1	B6
_					FETCH	97	2	88-2	D7
[KEYM SET]	22	2	88-1	B6	KEYM	23	14	88-1	A6
KEY SEEN*									_
(F/F)	2	6	**	B8	(RUN LOGIC)	21	1	**	B6
					(MR)	54 109	1	00.9	D8
VEV CEEN					$(\mathbf{MR})$	102	1	88-3	D8
KEISEEN (F/F)	9	5	99 1	29	VEV ENAD*	2	1	99 1	פת
(Г/Г)	4	5	00-1	DO	(SH)	23	1 1 3	1-00	
						20	10		
LDA·E*	52	10	88-2	В4	(Pack Logic)	99	1	88-3	D5
LOAD AC*	93	6	88-3	D2	(	(A77)	-	90-1	
		-			ACD	123	3	88-4	B8
					ACS	124	3	**	B7
LOAD ACB	100	11	88-3	C3	SHIFT ACB	100	2	88-3	C3
					ACB(LD)	105	10	88-4	B4
					ACB(LD)	107	10	''	B4
					ACB(LD)	108	10	**	B4
LOAD CRY*	97	8	88-3	C5	CARRY	76	11	88-3	C5
					(Pack Logic)	99	5	,, ,,	C5
LOAD IR	34	3	88-2	A6	TD(TD)	(A73)	10	90-1	10
					IR(LD) IR(LD) Loria	28	10	88-2	
					IR(LD) LOgIC	0 30	10	,	
					MBC(LD)	33	10	.,	Δ5
					[STUTTER]	54	15	88-1	D7
*Indicates ''Not''						~ 1			~,

SIC	SNAL	LIST	

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O	RIGIN	_			DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
LOAD MBO*	98	8	88-3	A2	MBO(SH) MBO(SH) MBO(SH) MBO(CH)	37 38 39	13 13 13	88-4	C4 C4 C4
LOAD PC* LOOP	57 103	8 7	88-3 ''	A2 D5	MBO(SH) PC MB LOAD LOOP* S0 (IO Inst DCDR)	40 119 13 22 47 64	13 12 12 5 9 5	 88-1 88-3 88-2 88-1	C4 A6 C3 D5 C3 B5
LOOP*	22	6	88-3	D5	PTG2·LOOP PC IN* CON INST*	70 35 36	4 5 10	., 88-2 88-1	D5 D5 A2
LOOP SET	83	2	88-3	D5	MA LOAD* (TS3/TS0) PTG-5	56 65 70	13 9 10	·''	D3 C5 D5
LOOP SET*	104	8	88-3	D5	LOOP DCHA SET* LOOP SET	103 71 83	2 12 1	88-3 88-1 88-3	D5 C5 D5
MA1 MA1* MA2 MA2* MA3 MA3* MA4 MA4* MA4B* MA4B* MA4B MA5 MA55 MA5B	33 33 33 33 29 29 67 67 29 29 67	15 14 10 11 9 8 16 1 4 10 15 14 6	103-1   103-4 103-4 103-1  103-4	C7 C7 C7 C7 C7 C7 C7 C7 C7 D8 D8 C6 C6 C6	[ SARD1 ] (Jumper) [ SARD1 ] '' [ SARD2 ] '' [ SARD2 ] '' [ SARD2 ] '' [ SARD3 ] '' [ SARD4 ] '' [ SARD2 ] '' [ SARD3 ] '' [ SARD4 ] '' [ SARD5 ] '' [ MA4B '' '' '' '' '' '' '' '' '' '' '' '' ''	35 35 35 35 35 67 67 52 66 54 62 67 67	$\begin{array}{c} 4\\ 4\\ 1\\ 2\\ 3\\ 5, 4\\ 5, 4\\ 5, 4\\ 5\\ 9\end{array}$	103-1  103-4  103-4  103-4	D8 D8 D8 D8 D8 D8 D8 7 7 7 7 7 7 7 7 8 8 8 8
'Indicates ''Not''									

O	RIGIN				DESTINATION				
SIGNAL	СНІ₽	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
					Y ADDR DCDR	54	7	103-4	7
	1				**	62	7	••	7
	1					52	7	**	7
	0.7		100 4	<u></u>	"	66	7	"	1
MA5B*	67	8	103-4		Y ADDR DCDR	54	$\frac{1}{1}$	103-4	7
					••	62 50	1		
					••	52	1		7
MA6	29	10	103-1	C5	MA6B*	67	1	,,	B8
MA6*	29	11	100-1	C5	MINOD		1		20
MA6B*	67	2	103-4	B8	MA6B	67	13	103-4	B8
	•••				Y ADDR DCDR	62	6	11	7
					"	66	6	••	7
MA6B	67	12	103-4	B8	**	54	6		7
					**	52	6	**	7
MA7	29	9	103-1	C5	MA7B*	44	11	**	A8
MA7*	29	8	••	C5					
MA7B*	44	10	103-4	A8	MA7B	44	3	103-4	A8
					Y ADDR DCDR	60 50	5, 4		A
14470			100 4	A 0		50	5,4		A
MATB	44	4	103-4	Ao	••	57	5,4 5 1		
νταθ	25	16	103 1	$C^4$	ΜΛΩΦ*	41	0,4	103 /	
MAO MA8*	25	10	, ''	C4	MAOD	77	9	103-4	110
MA8B*	44	8	103-4	A8	MA8B	44	5	103-4	A8
		Ũ			Y ADDR DCDR	60	7	11	Α
					-,,	50	7	• •	Α
					,,	57	7	**	Α
					,,	47	7	• • •	A
MA8B	44	6	103-4	A8	,,	60	1	**	Α
					11	50	1	••	A
					''	57	1	**	A
				~ 4	**	47	1	,,	A
MA9	25	15	103-1	C4	MA9B*	44	13	,,	Að
MA9*	25	]4		C4					
*Indicates '' Not''									<i></i>

O	RIGIN	-			DES	'TINA	TION	1	
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
MA9B*	44	12	103-4	A8	MA9B	44	1	103-4	A8
			]		Y ADDR DCDR	60	6	''	А
					11	57	6	11	A
MA9B	44	2	103-4	A8		50	6		A
MA10	25	10	103_1	C4	MA10B*	47	0	••	
MAIO*	25	11	103-1	C4	MAIUD	13.	ľ		
MA10B*	71	4	103-3	D8	MA10B	71	11	103-3	D8
		-			X ADDR DCDR	73	5.4	''	7
			ĺ		"	77	5.4		7
MA10B	71	10	103-3	D8	••	72	5, 4	11	7
				<b>í</b> 1	11	76	5, 4	**	7
MA11	25	9	103-1	C4			ŕ		
MA11*	25	8	**	C4	MA11B	71	5	103-3	C8
MA11B	71	6	103-3	C8	MA11B*	71	9	**	C8
				1	X ADDR DCDR	72	7	11	7
					**	76	7	**	7
					11	73	7	**	7
			100.0	~	11	77	7		$\frac{7}{2}$
MA11B*	71	8	103-3	C8	**	72	1	,,	$\frac{7}{7}$
						76			7
					••	73			
M A 19	22	16	102 1	C3	MA19D*	71		102 2	
MA12 MA19*	44 22	10	103-1		MAIZD	11	1	102-2	Do
MA12 MA19B*	71	2	103-3	B8	MA12B	71	13	103-3	<b>B</b> 8
	11	2	100-0	20	X ADDR DCDR	76	6	100-0	7
		j				77	6	**	7
MA12B	71	12	**	B8	**	72	6	11	7
	. –				**	73	6	11	7
MA13	22	15	103-1	C3	MA13B*	80	11	••	A8
MA13*	22	14	*1	C3					
MA13B*	80	10	103-3	A8	MA13B	80	3	103-3	A8
					X ADDR DCDR	79	5,4	11	Α
					11	74	5,4	11	Α
MA13B	80	4	103-3	A8	X ADDR DCDR	78	5,4	**	Α
	1				''	75	5,4	''	Α
*Indicates ''Not''									

O	RIGIN				DESTINATION				
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MA14	22	10	103-1	C2	MA14B*	80	9	103-3	A8
MA14*	22	11	''	C2		1			
MA14B*	80	8	103-3	A8	MA14B	80	5	103-3	A8
					X ADDR DCDR	79	7	**	Α
					11	74	7	**	A
					**	78	7	11	A
			100 0		**	75	7	**	A
MA14B	80	6	103-3	A8	**	79	1		A
					**	74	1	**	A
						78			A
76415			102 1	<b>C</b> 2	MAIED*	75	1		
	22	9	103-1	$C_2$	MA19B*	84	13		Ao
MAI5* MAI5D*	22 90	0	103 3		MA15D	90	1	102 2	48
MAIJD	00	14	103-3	AU	Y ADDR DCDR	70	6	103-5	
						78	6	••	A
MA15B	80	2	103-3	A8	**	74	6	**	A
MILLOD	00		100 0		**	75	6	**	A
MA LOAD*	60	8	88-1	D2		(B7)		90-1	
					MTG(SH)	35	11	88-1	C7
					[MA LOAD]	30	9,10	103-1	C8
					11	30	12,		
							13	**	C8
[MA LOAD]	30	8	103-1		MA1-3	33	13	103-1	
-						33	4	**	
					MA4-7	29	13	**	
						29	4	**	
					MA8-11	25	13	**	
					34410 15	25	4		-
	2.2	E	00 9	<b>A E</b>	MA12-15	22	13	00 2	
MBC8+	33	Э	00-2	АЭ	(SKIP LUGIC)	°11 977	9 1	00-3 88 9	
					MBC(DS)	22	4	11	Δ5
					(SH/SWD DCDB)	51	3	**	B6
					(IO DCDR)	63	3	88-1	A4
					11	63	13	11	A4
*Indicates ''Not''									

O	RIGIN				DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MBC8	27	2	88-2	A4	(SKIP LOGIC)	11	5	88-3	B7
					S0	47	5	88-2	C3
MBC9*	32	5	88-2	A4	(SH/SWP DCDR)	51	2	**	B6
					(IO DCDR)	63	2	88-1	A4
				[		63	14	''	A4
					MBC9	79	9,	00.0	
MDC0	70	0	00 9	12	(SKID LOCIC)	0.0	10	88-2	A4
	19	0	00-2	AS	(SKIP LOGIC)	80	1	88-3	BO
	- 55	9	00-2	AS	CDV ENAD	21	9	00-2	A4
MBC10	97	ß	88-2	4	CDU INST*		5	00-0	
	21		00-2			8	a	88-1	
MBC11*	32	9	••	Δ4	MBC11	27	13	88-2	
MBC11	27	12	••	A3	DS1*	8	11	88-1	C4
					CPU INST*	9	4	88-2	B8
	1				CRY ENAB	77	5	88-3	C7
MBC12*	33	7	88-2	A5	MBC12	27	11	88-2	A4
MBC12	27	10	88-2	A4	DS2*	8	13	88-1	C4
					<b>CPU INST*</b>	9	2	88-2	D8
	[				LOAD CRY*	101	1	88-3	C6
					S MULT	116	3	88-4	C7
MBC13*	32	7	88-2	A4	MBC13	27	3	88-2	A3
MBC13	27	4	11	A3	DS3*	22	9	88-1	C4
				l l	CPU INST*	9	1	88-2	B8
					(SKIP LOGIC)	77	1	88-3	B7
			00.0		S MULT	116	6	88-4	C7
MBC14*	33	11	88-2						
(NOT USED)		10	00 0	4.5	DC/+		2	00 1	04
MBC14	აა	12	00-2	AO		10	3 1	00-1	C4 D0
					(SKID I OCIC)	77	10	88.3	. D0 В7
					S MULT	116	13	88-4	
MBC15*	32	11	88-2	Δ4	(SKIP LOGIC)	80	4	88-3	B6
MBC15	32	12		A3	DS5*	8	1	88-1	C4
MID010	02				CPU INST*	10	2	88-2	B8
					S MULT	116	10	88-4	C6
*Indicates ''Not''									
					r i				1

0	RIGIN				DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MB CLR* [MB CLEAR]	19 18	6 8	88-1 103-1	D2 B8		(B86) 30	2,4,	103-1	B8
[MB CLEAR · SEL]	30	6	"	B8	INH0 F/F INH1 F/F INH2 F/F INH3 F/F INH4 F/F INH5 F/F INH5 F/F INH6 F/F INH7 F/F INH7 F/F INH10 F/F INH10 F/F INH11 F/F INH13 F/F INH14 F/F INH15 F/F	34 32 32 31 31 28 28 27 27 24 24 23 23 21 21	5 13 1 1 13 13 1 1 13 13 1 1 13 13 1 1 1 13 13	103-1 103-1 "" " " " " " " " " " " " " " " " " "	B8 B B B B B B B B B B B B B B B B B B
MB LOAD	14	6	88-1	C2		(B74) 36	9	90-1 103-1	B8
[MB LOAD· SEL]	36	8	103-1	B8	INH0 F/F INH1 F/F INH2 F/F INH3 F/F INH4 F/F INH5 F/F INH5 F/F INH6 F/F INH7 F/F INH8 F/F INH9 F/F INH10 F/F INH11 F/F INH12 F/F INH13 F/F INH14 F/F	34 32 32 31 31 28 27 27 24 24 23 23 21	$     \begin{array}{r}       11 \\       3 \\       11 \\       11 \\       3 \\       11 \\       11 \\       3 \\       11 \\       11 \\       3 \\       11 \\       11 \\       3 \\       3 \\       11 \\       3 \\     $	103-1  103-1       	B B B B B B B B B B B B B B B B B B B
*Indicates ''Not''						<u> </u>	Ŭ		2

O	RIGIN				DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MDOOX	40	E	00 4	DI	INH15 F/F	21	11	103-1	В
MIBOO .	40	5	00-4	D4	[ MD0 ]	(Б79) 17	9	103-1	A7
MBO1*	39	5	88-4	D3	MB1	(B77) 17	5	103-1	A7
MDON*	9.7	_	00 4		(CON IND) (P14)	7	11	89-1	D7
MBO2*	31	Э	88-4	C4	MD2	(B44) 15	9	103-1	A7
MBO3*	38	5	88-4	C3	(CON IND) (P15)	7 (B43)	5	89-1	D7
		-		00	MD3	15	5	103-1	A6
MBO4*	40	7	88-4	D4	(CON IND) (P38)	о (B42)	9	89-1	ים
					MD4 (CON IND) (P16)	13 8	9 11	103-1 89-1	A6 D6
MBO5*	39	7	88-4	D3		(B32)		102 1	۸ <i>C</i>
					(CON IND) (P11)	13 8	ว 5	89-1	D6
MBO6*	37	7	88-4	C4	MD6	(B16) 11	9	103-1	A5
MD07*	20	77	00 /	<b>C</b> 2	(CON IND) (P35)	9 (P14)	9	89-1	D6
MBO1*	30	1	00-4	C3	MD7	(B14) 11	5	103-1	A5
MBO8*	40	9	88-4	D4	(CON IND) (P9)	9 (B12)	11	89-1	D5
					MBO12 SAVE*	42	2	88-1	C8
					(CON IND) (P18)	9	5	89-1	D5
MBO9*	39	9	88-4	D3	MD9	(B9) 9	5	103-1	C4
MPO10*	37	٩	88_4	C4	(CON IND) (P8)	10	9	89-1	D5
WIDOIO	31	9	00-4	Ŭ,	MD10	7	9	103-1	C4
MBO11*	38	9	88-4	C3	(CON IND) (P44)	10 (B5)	11	89-1	D4
	l				MD11 (CON IND) (P6)	7	5 5	103-1 89-1	C4 D4
*Indicates ''Not''						10	U	00-1	51

0	ORIGIN					DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRII	
MBO12*	40	11	88-4	D4		(A39)				
					MD12	5	9	103-1	A3	
					(CON IND) (P30)	11	9	89-1	D4	
MBO12	40	12	88-4	D3	D MULT	121	3	88-4	C8	
[					MULT	120	6	**	D6	
					ADDER TEST	57	12	88-3	A4	
MBO13*	39	11	88-4	D2		(A37)				
					ADDER TEST	60	5	88-3	A4	
					MD13	5	5	103-1	A3	
					(CON IND) (P4)	11	11	89-1	D3	
MBO13	39	12	88-4	D2	D MULT	121	6	88-4	C8	
					MULT	120	3	**	D6	
MBO14*	37	11	88-4	C4		(A43)				
					ADDER TEST	60	4	88-3	A4	
					MD14	3	9	103-1	A3	
	0.77				(CON IND) (P12)	11	5	89-1	D3	
MBO14	37	12	88-4	C3	D MULT	121	13	88-4	C7	
					MULT	120	21		C6	
MBO15*	38	11	88-4	C2	10015	(A41)	_	100 1		
					MD15	3	5	103-1	A2	
10000		10	00.4		(CON IND) (P28)	11	1	89-1	D3	
MBO15	38	12	88-4	C2	ADDER TEST	84	9	88-3		
		i				120	10	88-4		
	40	_	00 1	07	MULT	121	18	00 9		
MBO12 SAVE*	42	1	88-1	01	SU	40	4	88-2		
	4.6	0	100 1		ADD ONE <sup>+</sup>	90	19	102 1	D4 707	
	17	0	103-1	B7		34	12	103-1	D ( זים	
MDI	1 1	0	103-1	B7		22	2	103-1		
MD9	1.4	0	103-1	<b>B</b> 7	INH9	30	2	,,	B7	
IVILDZ	10	°	103-1	Ъ	111112 M A 9	22	6	,,		
MD3	15	6	103-1	B6	INHS	32	19	,,		
10109	13	v	103-1	ЪU	MA3	33	7	,,	01 C7	
MD4	13	g	103-1	B6	INH4	31	12	**	B7	
14117-1	10	Ľ	100-1	20	MA4	29	2	11		
					111111				0.	
*Indicates ''Not''										

SIGNAL	LIST	

Table 1 - Nova 1210/1220

0	RIGIN				DESTINATION				
SIGNAL	СНІ₽	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MD5	13	6	103-1	B6	INH5	31	2	103-1	B6
				DE	MA5	39	3	**	C6
MD6	11	8	103-1	ВЭ	INH6	28	2	11	B5
MD7	11	c	102 1	<b>B</b> 5	MA6	29	6 19		C5
MD7	11	ю	103-1	D0		20	14		ВЭ С5
MD8	٩	Q	103-1	B5	INH8	29	12	11	C5 B5
101100	5	0	100-1	20	MA8	25	$\frac{12}{2}$		C5
MD9	9	6	103-1	В4	INH9	27	2	11	B4
11120	Ů	Ŭ	100 1		MA9	25	3	**	C4
MD10	7	8	103-1	B4	INH10	24	2	**	B4
					MA10	25 -	6	11	C4
MD11	7	6	103-1	B4	INH11	24	12	11	В4
					MA11	25	7	"	C4
MD12	5	8	103-1	B3	INH12	23	12	**	B3
				<b>D</b> 9	MA12	22	2	**	C3
MD13	5	6	103-1	B3	INH13	23	2	**	B3
			100 1	109	MA13	22	3		C3
MD14	3	8	103-1	ЪЭ		21	4		B3 C2
MD15	2	G	102 1	B2		22	12	11	ເວ ເຊ
WID15	J	0	105-1	102	MA15	$\frac{21}{22}$	12	103-1	$C^2$
MULTIPLY/						20	•	100 1	02
DIVIDE	SEL								
MD SEL1*	(A87)		88-2	C5	ACS1 SEL*	49	6,8	88-2	C4
MEM0*	<b>`16</b> ´	3	103-1	<b>B</b> 7		(B71)	ŕ		
(ACEX+ACDP)	1	3	89-1	A5	(CON IND) (P39)	7	9	89-1	C8
					IR0*	28	3	88 <b>-2</b>	A6
					MBO0*	40	3	88-4	D4
					Defer Again	76	2	88-2	C7
					(EFA LOGIC)	55	10,		
	1.0		100 1	707			13	88-3	C6
MEM1*	16	6	103-1	Δ1 Δ5	(CON IND) (D41)	(B.10)	12	QA 1	07
(ACDP)	T	Ø	09-1	лu	(CON IND)(P41) IR1*	29	2	88_9	
				j	MBO1*	39	3	88-4	D3
					(EFA LOGIC)	55	9	88-3	C6
*Indicates ''Not''					(0010)		,		

0	RIGIN				DESTINATION				
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MEM2* (DP+DPN)	14 2	3 8	103 -1 89-1	В7 А4	(CON IND) (P13) IR2* MBO2*	(B47) 7 29 37	3 15 3	89-1 88-2 88-4	C7 A7 C4
MEM3* (ACEX+ ACDP)	14 1	6 11	103-1 89-1	B6 A7	(EFA LOGIC) (CON IND) (P43) IR3*	55 (B68) 7 29	1 1 14 2	88-3 89-1 88-2	C6 C7 A7 C3
MEM4* (ACEX+ACDP)	12 1	3 8	103-1 89-1	B6 A6	(CON IND) (P37) IR4* MBO4*	(B28) 8 29 40	3 13 3 2	89-1 88-2	C6 A7 D4
MEM5*	12	6	103-1	B6	MDO4	(B26)	4	00-4	
ACDP)	2	11	89-1	A3	(CON IND) (P36) IR5* MBO5*	8 28 39	3 2 2	89-1 88-2 88-4	C6 A6 D3
MEM6*	10	3	103-1	B5	mboo	(B22)	-	00 1	
DPN)	2	3	89-1	A3	(CON IND) (P10) IR6* MBO6*	8 28 37	1 15 2	89-1 88-2 88-4	C6 A6 C4
MEM7* (EXN+DPN)	10 2	6 6	103-1 89-1	В5	(CON IND) (P42) IR7* MB07*	(B24) 9 28 38	13 14 2	89-1 88-2 88-4	C5 A6 C3
MEM8*	8	3	103-1	В5	(CON IND) (P34) MBC8* MBO8*	(A55) 9 33 40	3 3 15	89-1 88-2 88-4	C5 A5 D4
MEM9*	8	6	103-1	В4	(CON IND) (P7) MBC9* MBO9*	(A53) 9 32 39	1 3 15	89-1 88-2 88-4	C5 A4 C3
*Indicates ''Not''									

O	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MEM10*	6	3	103-1	B4	(CON IND) (P32) MBC10*	(A45) 10 33	13 15	89-1 88-2	C4
MEM11*	6	6	103-1	В4	MBO10* (CON IND) (P31)	37 (A51) 10	15 3	88-4 89-1	C4 C4
MEM12*	4	3	103-1	В3	MBC11* MBO11*	32 38 (A36) 10	15 15 1	88-2 88-4 89-1	A4 C3 C4
MEM13*	4	6	103-1	В3	MBC12* MBO12*	33 40 (A35)	2 14	88-2 88-4	A5 D4
		-			(CON IND) (P29) MBC13* MBO13*	11 32 39	13 2 14	89-1 88-2 88-4	C3 A4 D2
MEM14*	2	3	103-1	B2	(CON IND) (P3) MBC14*	(B76) 11 33	3 14	89-1 88-2	C3 A5
MEM15*	2	6	103-1	B2	MBO14* (CON IND) (P2)	37 (B18) 12	14 13	88-4 89-1	C4 C3
MEM CLK	73	6	88-1	<b>A</b> 6	MBC15* MBO15* (MTG)	32 38 (B48) 17	14 14 6	88-2 88-4 90-1 88-1	A4 C2 D6
					(KEY/RUN/DCH) (ACTG) LOAD AC* S BUFF D BUFF	23 54 93 115 122	6 6 4 6	'' 88-3 88-4 ''	C6 D8 D3 C7 C8
MEM OK	(A9)		91	B2	IR4, IR1-3 RUN LOGIC	29 62	6 5	88-2 88-1	A8 C7
*Indicates ''Not''									

#### <u>Table 1 - Nova 1210/1220</u>

0	RIGIN				DESTINATION				
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[ MSKO] MSKO* MSTP	4 5 (A20)	11 4 (P48	88-1  ) 89-1	B4 A4	MSKO* (RUN LOGIC)	5 (A38) 24	3 1,	88-1 90-1	A4
MTG0	17	5	88-1	D6	INHIBIT DCHI MTG0* MTG	13 14 16 17	10 10 13 13 2,	88-1 '' ''	B7 C2 C2 D6
MTG0* MTG1	16 17	12 7	88 -1 88 -1	D6 D6	READ1* MB CLR* MTG(SH)(Logic) RQENB* MTG1*	19 19 36 16 16	15, 14 1 4 5 11	11 11 11 11 11 11	D6 D2 D2 C7 C2 D6
MTG1*	16	10	88-1	D6	READ2* MB CLR* DCHO	19 19 18	10 5 10	**	D2 D2 B2
MTG3*	17	12	88-1	D6	MTG(DS) MTG(DS) STROBE	36 17 18	5 4 1,2, 4	**	D6 D6 D2
MULTO* MULT1* MULT2* MULT3*	120 120 120 120 120	10 11 13 14	88-4 '' ''	CD 5 '' ''	READ1* READ2* MBO(DS) MBO(DS) MBO(DS) MBO(DS)	19 19 40 39 37 38	2 9 4 4 4 4	'' 88-4 '' ''	D2 D2 CD34 "
OVFLO	15	8	88-1	B2		(B39)		90-1	
PACK PACK*	103 83	9 12	88-3 88-3	D5 D5	ACS1 SEL* ACS2 SEL* PACK* ACS1 SEL* ACS2 SEL*	49 49 83 49 49	10 12 13 4 2	88-2  88-3 88-2 	C5 B5 D5 C5 B5
*Indicates ''Not''					LUAD AC*	111	Э	88-3	D3

01	RIGIN				DESTINATION				
Y									
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[ PC0]	119	10	88-4	A5	MULT0*	120	10	88-4	CD 5
[ PC1 ]	119	9	11	A5	MULT1*	120	11	**	CD 5
[ PC2 ]	119	7	**	A5	MULT2*	120	13	**	CD 5
[ PC3 ]	119	6	11	A5	MULT3*	120	14	**	CD 5
PC ENAB*	61	8	88-3	B3	PC IN*	36	1	88-2	D5
					LOAD PC*	57	5	88-3	B3
					E SET	74	2	88-2	C7
PC IN*	36	3	88-2	D4	PC	119	11	88-4	A5
					Multiplexer	120	7, 8		
							9	88-4	C5
					MULT(ENAB)	120	7,8,		
							9	88-4	C5
PI	95	11	88-2	D6	PC IN*	35	4	88-2	D5
					ADD ONE*	90	3	••	D4
					CLR SKIP*	100	5	88-3	A4
					Disable D Mult	46	2,3	88-2	B3
PI*	95	12	88-2	D6	IR(SH)	114	2	88-2	A8
					IR(DS)	12	13	**	A8
					D SET	74	11	••	C7
					ADD ONE*	82	13	**	D3
					ION*	84	1	**	C7
					LOOP SET*	84	12	88-3	D6
PI SET	96	6	88-2	C6	PI	95	14	**	
					FETCH	96	9	**	D6
					LOAD MBO*	98	2	88-3	A3
PL*	(A19)	(P23	89-1	B2	KEYM·PL	41	9	88-1	C6
					(RUN Logic)	43	3	**	B7
					Disable D Mult	87	9	88-2	B4
PRESET*	22	10	88-1	B7	MTG(MR)	17	1	88-1	D7
					INPUT	66	1	''	B5
					PTG(MR)	69	1	••	D5
					SKIP	78	1	88-3	B5
					(Major States)	95	1	88-2	D7
PTG0	69	9	88-1	D4	PTG DCDR	68	2	88-1	D3
					**	68	14	11	D3
					PTG	69	14	''	D4
					PC	119	4	88-4	A5
*Indicates ''Not''					PC	119	13	''	A5

# <u>Table 1 - Nova 1210/1220</u>

O	RIGIN				DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
PTG1	69	11	88-1	D4	MB LOAD EFA·PTG1 PTG DCDR	112 34 68	13 4 3	88-1 88-2 88-1	C3 A3 D3
					End Cycle F/F PC PC MB LOAD	08 113 119 119 119	13 3 5 14	,, 88-4 ,,	D3 D5 A5 A5
PTG1*	69	12	88-1	D4	SO PTG	47 69	10 2 15	88-1 88-2 88-1	C3 C3 D4
PTG2*	68	10	88-1	D4	ADDER Test TS0/TS3 PTG2 PTC2: LOOP	57 65 67 70	13 10 9 5	88-3 88-1	A6 C5 D3
PTG2 PTG5	67 70	8 8	88-1 88-1	D3 D4	INPUT F/F Key/Run/DCH/	66 22	5 12	·' 00 1	Do B5
					(LD) (LD) TS0/TS F/F Adder Test ''	42 66 78 79	10 10 2 12 4	88-3	C6 C8 C5 A5 A5
		0	00.1	50	Major States (LD) LOAD MBO* LOAD MBO*	95 98 98	10 3 4	88-2 88-3 88-3	D7 A3 A3
PTG5 ENAB*	68	б	88-1	D3	INH TRANS* PTG5 Pack Logic SKIP F/F	56 70 70 79	1 9 12 12	88-1  88-3 	B2 D5 C6 B5
PTG=0∙TS0	113	9	88-1	A5	Adder Test MA LOAD* ADD ONE*	58 60 88	12 13 12 9	" 88-1 88-2	C3 A6 D2 D3
PTG=0∙TS0*	113	8	88-1	A5	ADD ONE* Shifter Logic SHIFT ACB	90 88 90 93	9 4 13 10	88-4 88-2 88-4 88-3	A7 D3 A7 C4
*Indicates ''Not''									

T1-33

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#### SIGNAL LIST

#### <u>Table 1 - Nova 1210/1220</u>

	O	RIGIN				DESTINATION					
	SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
	PTG=0.TS3*	68	4	88-1	D3	$PTG=0 \cdot TS3$	67	13	88-1	D3	
		67	19	00 1	D2	ADD ONE*	88	5	88-2	D3	
	P10=0.122	01	12	00-1	D3	INFUL F/F	9	9, 10	88-1	C5	
						MTG(LD)	17	10	11	D7	
		1				ADD ONE*	88	1, 2	88-2	D3	
	PTG=1.TS0*	68	11	88-1	D3	ADDER Test	80	10	88-3	A6	
			_			SHIFT ACB	93	11	"	C4	
	$PTG=1 \cdot TS3*$	68	5	88-1	D3	$\frac{(\text{IO DCDR})}{\overline{\text{DBRGR}}}$	109	5	88-1	A5	
	PTG2·LOOP	70	6	88-1	D4	PTG2+LOOP	73	13	88-1	D4	
						LOAD MBO" LOOP SET*	90 104	9 3 4	00-J 88_3	В3 D6	
	PTG2+LOOP	73	12	88-1	D4	LOAD IR	34	з, т 1	88-2	D0 A7	
	1100, 1001			001	5.	SKIP $(F/F)$	79	2	88-3	B5	
	PULSE ENAB	109	6	88-1	A5	OVFLO	15	12	88-1	B2	
						IO DCDR	62	1	**	A5	
	PWR FAIL*	(A5)		91-1	C2	PWR LOW	86	12	88-3	D8	
						AC CLR	20	12	88-1	A6	
I	PWR LOW	102	11	88-3	D7	(SKIP Logic)	11	1	88-3	B1	
1	PWR LOG*	102	12	.,	D7	PI SET	75	13	88-2		
	<b>PFAD1</b> *	10	ર	88_1	פת	PWK LOW	00 (B87)	10	00-3 103_1	D0	
	ILBADI	10	Ŭ	1-00	102	MTG(SH)	35	10	88-1	D6	
1						READ 1B	18	13	103-1	D6	
		18	12	103-1	D6	11	19	5, 4	103-1	D6	
						READ2B	19	12	103-1	D6	
	READ 1B	19	6	103-1	D5	**	19	10	"		
						(X ADDR DCDR)	72	2	103-3	A7	
						**	70	2		A7	
						**	77	4 2	••		
						••	79	3	**	A7	
						11	74	3	,,	A7	
						**	78	3	**	A7	
						••	75	3	11	A7	
		1									
,	'Indicates ''Not''										

O	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
READ 2*	19 18	8 10	88-1 103-1	D2 D6	READ 2B	(B90) 18 19 19	11 9 13	103-1 '' ''	D6 D6 D6 D6
READ 2B	19	8	103-2	D5	(Y ADDR DCDR) " " " " " " "	54 62 52 66 60 50 57 47	22223333	103-4 '' '' '' '' ''	A7 A7 A7 A7 A7 A7 A7 A7
READ IO*	12 18	3	88-1 103-1	B2 A8	[READ IO] [MD0] MD1 MD2 MD3 MD4 MD5 MD6 MD7 MD8 MD9 MD10 MD11	(B83) 18 17 17 15 15 13 13 11 11 9 9 7 7	3 13 2 13 2 13 2 13 2 13 2 13 2 13 2	103-1 	A8 A8 A A A A A A A A A A A A A
[READ IO] *Indicates ''Not''	18	6	103-1	Α8	MD12 MD13 MD14 MD15 [MD0] MD1 MD2 MD3 MD4 MD5 MD6	5 5 3 18 17 17 15 15 13 13 11	13 2 13 2 5 10 4 10 4 10 4 10 4 10	 103-1      	A A A A A A A A A A A A

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0	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
					MD7 MD8	11 9	4 10	103-1 ''	A A
				[	MD9	9	4	**	Α
					MD10	7	10	**	A
					MD11	7	4	**	A
					MD12	5	10	**	
					MD13	5	4		A A
	1				MD14 MD15	3	10	••	
DFSFT*	22	4	881	<b>B</b> 7	DDFSFT*	3 3	4	99.1	D7
		Т	00-1	D	IORST	10	13	11 00-1	
	ł				101001	21	9	**	B8
					KEY/RUN/DCH		Ŭ		20
	1				(MR)	23	1	**	C6
	1				(MR)	42	1	11	C8
					ION*	84	2	88-2	C7
					LOOP/PACK				
					(MR)	103	1	88-3	D5
RESTART*			88-1	A8	KEY SEEN F/F	3	5	88-1	B8
					Disable D Mult	87	10	88-2	B4
RELOAD							10		
Disable*	(B72)					36	10,	102 1	<b>B</b> 8
RESTART							12	103-1	20
Enable	(A32)	(P19	89-1	B7					
RINH0	(A5)	(	103-2	7					
RINH1	(A7)		11	7					
RINH2	(A9)		**	7					
RINH3	(A11)		11	7					
RINH4	(A13)		**	7					
RINH5	(A15)		**	7					
RINH6	(A18)		**	7					
RINH7	(A17)			1					
KINH8 DINU0	(A19)		••	4 1					
RINH9 DINU10	(A24) (A22)		,,						
RINH11	(A23)		11	4					
*Indicates ''Not''	(*****)			-					

OI	ORIGIN					DESTINATION				
SIGNAL	СНІР	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
RINH12 RINH13 RINH14 RIN15 RQENB* RST* RUN RUN* S0 S1 S2 [S BUFFR0] [S BUFFR1] [S BUFFR1] [S BUFFR3] SELB* SELD* SELD* SELECT	(A28) (A25) (A29) (A27) 16 (A30) 23 22 91 91 91 115 115 115 (A82) (A80) 35	6 (P20 7 12 3 8 11 5 7 9 11 8	103-2 " 88-1 89-1 88-1 88-1 88-1 88-2 " 88-4 " 90-1 90-1 103-1	4 4 4 4 C2 B6 C6 C6 C2 C2 C2 C2 C2 C7 C7 C7 C7 C7	RESET* RUN* CPU CLK (CON IND) (A14) KEY SEEN F/F ADDER '' S1 ADDER S MULT '' '' SKIP Logic '' STRB A, B, C, D '' READ 1B INH GATE A, B '' (DRIVE IO)	$(B41) \\ 21 \\ 22 \\ 72 \\ 12 \\ 2 \\ 117 \\ 117 \\ 91 \\ 117 \\ 116 \\ 116 \\ 116 \\ 116 \\ 116 \\ 111 \\ 1 \\ $	$12 \\ 13 \\ 4, 0 \\ 1 \\ 1, 2 \\ 3, 6 \\ 5 \\ 4 \\ 4 \\ 2 \\ 5 \\ 14 \\ 11 \\ 10 \\ 4 \\ 1, 10 \\ 12, 13 \\ 1, 2 \\ 2, 4, 5 \\ 10, 12, 13 \\ 13 \\ 13 \\ 13 \\ 13 \\ 13 \\ 13 \\ 13 $	90-1 88-1 " 89-1 88-1 88-4 " 88-2 88-4 " " 88-3 " 103-1 " " "	B8 C6 A7 D2 B8 D8 D8 C3 D8 C7 C7 C7 C7 C7 C7 C7 C7 B6 B6 D4 D5 D6 D3 C8	
*Indicates ''Not''										

0	RIGIN			<b>T</b>	DES	TINA	ΓΙΟΝ			
SIGNAL	СНІ₽	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
					(INH TRANS*)	36	1	103-1	B8	
	1				(MB LOAD)	36	13	**	B8	
					(MB CLEAR)	30	1	**	B8	
SERIAL CRY	54	12	88-1	D7	OVFLO	15	13	88-1	B2	
	Į –				ADD ONE*	88	6	88-2	D3	
SET ION*	63	10	**	B8	ION*	82	4	**	C7	
SHIFT0*	125	13	88-4	A 678		(B94)				
					SKIP Logic	110	12	88-3	A6	
					ACD	123	4	88-4	A 678	
	105	1.4	00.4		ACS	124	4	**	l "I	
SHIFTI*	125	14	88-4			(B96)	10	00 9		
					SKIP Logic	110	10	88-3		
					ACD	123	0	00-4	A 0 18	
CUI TT9*	195	11	00 /	,, I	ACS	124 (D03)	0			
5111112	120	11	00-4		SKID Logic	110	12	88-3	16	
						123	10	88_4	A 678	
					ACS	120	10	11	A 0 10	
SHIFT3*	125	10	88-4	,,	ACD	124	10			
	120	10	00 1		SKIP Logic	110	9	88-3	AG	
					ACD	123	12	88-4	A 678	
					ACS	124	12	11	11 0 1 0	
							~ -			
SHIFT ACB	100	3	88-3	C2	ACB(SH)	105	13	11	B4	
					ACB(SH)	106	13	**	B4	
					ACB(SH)	107	13	11	B4	
					ACB(SH)	108	13	11	B4	
SHL*	51	6	88-2	B6	Carry F/F Logic	101	5	88-3	C6	
					[SHL]	101	3	11	C6	
					SHIFTER(SEL)	125	16	88-4	A8	
[SHL]	101	4	88-3	C6	CRY SET*	81	2	88-3	C6	
SHR*	51	5	88-2	B6	Carry F/F Logic	81	6	''	C6	
						101	5	"	C6	
(					SHIFTER (SEL)	125	17	88-4	A8	
[ SHR ]	101	6	88-3	C6	CRY SET*	81	1	88-3	C6	
1										

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#### SIGNAL LIST

#### <u>Table 1</u> - Nova 1210/1220

O	RIGIN			DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
SKIP SKIP* SKIP INC*	78 78 42	5 6 12	88-3 '' 88-1	B5 B5 C7	ADD ONE* IR0+ SKIP D SET ADD ONE* Test Skip Set PC IN*	90 (B69) 50 74 82 86 35	2 2 3 12 4 13	88-2 90-1 88-2 '' '' '' 88-3 88-2	D4 B6 C7 D3 A8 D5
					MA LOAD* PC ENAB* CLR SKIP*	56 58 99	$12 \\ 4,5 \\ 12$	88-1 88-3 ''	D3 B4 B3
+SL0 -SL0 +SL1 -SL1 +sl2 -SL2 +SL3 -SL3 +SL4 +SL5 -SL5 +SL6 -SL6 +SL7 -SL7 +SL8 -SL8 +SL9 -SL9 +SL10 -SL10 +SL11 -SL11			103-2	77777777777774444444444444444444444444	SNS0 " SNS1 SNS2 " SNS2 " SNS3 " SNS4 " SNS5 " SNS6 " SNS7 " SNS8 " SNS9 " SNS10 " SNS11 "	$\begin{array}{c} 69\\ 69\\ 69\\ 65\\ 65\\ 65\\ 59\\ 59\\ 59\\ 56\\ 56\\ 56\\ 56\\ 56\\ 49\\ 49\\ 49\\ 46\\ 46\\ 46\\ 46\\ 46\end{array}$	2 3 6 7 2 3 7 2 3 6 7 2 3 7	103-2	6666666666666633333333333
*Indicates ''Not''									

SIGNAL LIST	
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Table 1 - Nova 1210/1220

0	RIGIN			DESTINATION					
SIGNAL	СНІ₽	₽IN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
O SIGNAL + SL12 -SL12 + SL13 -SL13 + SL14 -SL14 + SL15 -SL15 [S MULT0] [S MULT1] [S MULT2] [S MULT3] SNS0 SNS0* SNS1* SNS1* SNS2* SNS3* SNS3* SNS4* SNS5*	RIGIN CHIP 116 116 116 116 116 116 116 116 116 11	PIN 4 7 12 9 14 8 12 6 14 6 12 8 14 8 12 6	DWG 103-2 " " " " " 88-4 " " 103-2 " " 103-2 " " " " " " " " " " " " " " " " " " "	GRID 4 4 4 4 4 4 4 4 4 4 4 4 4	DES FUNCTION SNS12 " SNS13 " SNS14 " SNS15 SNS15 ADDER ADDER ADDER ADDER " " " " SNS0* INH0 F/F SNS1* INH1 F/F SNS2* INH2 F/F SNS3* INH3 F/F SNS4* INH4 F/F SNS5* INH5 F/F	CHIP 40 40 40 40 40 38 38 38 38 38 38 38 38 38 38 38 38 38	FION PIN 2 3 6 7 2 3 6 7 2 3 6 7 1 8 20 22 1 9 10 5 4 9 10 5 4 9 10 5 4	DWG 103-2 " " " " " 88-4 " " " 103-2 103-1	GRID 3 3 3 3 3 3 3 3 3 3 3 3 3
SNS5 SNS6 SNS6 SNS7 SNS7 SNS7 SNS8 SNS8 SNS9 SNS9 SNS9 SNS9 SNS10 SNS10 *	56 55 55 49 48 49 48 48 48	14 6 12 8 14 8 12 6 14 6	11 11 17 17 17 17 17 17	6 6 6 3 3 3 3 3 3 3 3 3 3	INIIS F/F SNS6* INH6 F/F SNS7* INH7 F/F SNS8* INH8 F/F SNS9* INH9 F/F SNS10* INH10 F/F	55 28 55 28 48 27 48 27 45 24	4 9 10 9 10 5 4 5 4	103 -1 103 -2 103 -1 103 -2 103 -1 103 -2 103 -1 103 -2 103 -1	B6 B5 A6 B5 D3 B5 D3 B4 C3 B4

# <u>Table 1 - Nova 1210/1220</u>

0	ORIGIN					DESTINATION				
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
SNS11 SNS11* SNS12 SNS12* SNS13 SNS13* SNS14 SNS14* SNS14* SNS15 SNS15*	46 45 40 39 40 39 38 37 38 37	12 8 14 8 12 6 14 6 12 8	103-2 '' '' '' '' '' '' ''	3 3 3 3 3 3 3 3 3 3 3	SNS11* $INH11 F/F$ $SNS12*$ $INH12 F/F$ $SNS13*$ $INH13 F/F$ $SNS14*$ $INH14 F/F$ $SNS15*$ $INH15 F/F$	45 24 39 23 39 23 37 21 37 21	9 10 9 10 5 4 5 4 9 10	103-2 103-1 103-2 103-1 103-2 103-1 103-2 103-1 103-2 103-1	C3 B3 C3 B3 B3 B3 B3 B2 A3 B2	
STA·E* STOP* STOP INH* STOP SYNC STROBE	52 (A31) 82 102 18	11 (P45) 8 5 6	88-2 89-1 88-1 88-3 88-3 88-1	B5 B5 B6 D7 C2	LOAD MBO* MULT (SEL) STOP SYNC DCHA SET* SKIP INC* FETCH RUN Logic	99 120 4 71 87 97 43 (B20)	9 17 4,5 13 2 4 1	88-3 88-4 88-3 88-1 '' 88-2 88-1	B3 D8 C5 C8 D7 B7	
STRB A	1	6	103-1 103-1	D4 D4	STRB A, B, C, D SNS0* SNS1* SNS2* SNS3* SNS4*	1 68 68 64 64 58	5 10 4 4 10 10	103-1 103-2 '' ''	D5 C6 C6 C6 C6 A6	
STRB C	1	6	103-1	D4	SNS5* SNS6* SNS7* SNS8* SNS9* SNS10* SNS11*	58 55 55 48 48 45 45	4 4 10 10 4 4	•• •• •• •• ••	A6 A6 C3 C3 C3 C3	
STRB D *Indicates ''Not''	1	6	103-1	D4	SNS11* SNS12* SNS13* SNS14* SNS15*	45 39 39 37 37	10 10 4 4 10	103-2 '' ''	A3 A3 A3 A3	

				1					
0	RIGIN			<u> </u>	DESTINATION			[ 	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[STRT*] STRT [STUTTER] STUTTER* SWP*	63 7 54 73 51	6 4 9 2 4	88-1 '' '' 88-2	A4 A4 D7 D7 B6	STRT (IO STRT PLS) STUTTER* CPU CLK LOAD ACB	7 (A52) 73 72 100	3 1 1,13 13	88-1 90-1 88-1 88-1 88-3	A4 D7 A7 C3
TS3	66	5	88-1 88-1	C5	PC IN IR(SH) INST DCDR Disable D Mult KEYM · PL · TS0* PC ENAB* FETCH · TS0* PTG DCDR S1 LOOP SET* (D+E SET)+TS3 ACD OUT* ALC* PC ENAB* PC ENAB* IO DCDR Logic PTG DCDR	35 114 92 53 57 61 64 68 91 34 36 45 50 61 109 68	$3 \\ 5 \\ 10 \\ 1 \\ 9 \\ 10 \\ 13 \\ 12 \\ 4 \\ 10 \\ 1 \\ 2,4 \\ 2 \\ 15 $	88-2 " 88-3 " 88-2 88-1 88-2 88-3 88-2 " " 88-3 88-1 " "	D5 B8 B5 B3 C4 B4 D5 D3 C3 C6 D5 B3 B8 B4 B4 A5 D3
TS3 SET TEST* TEST SKIP Test Skip Set WAS JSR WAS JSR* WHOA* + 5 OK *Indicates ''Not''	65 (A92) 102 86 103 48 (B6) (A8)	8 7 3 5 8	88-1 90-1 88-3 '' 88-3 88-3 88-2 90-1 91-1	C5 D7 D7 C5 B2	ACTG(LD) Defer Again (F/F PTG=0·TS0 '' CARRY F/F SKIP F/F Logic RUN LOGIC STOP INH* TEST SKIP ACS1 SEL* SHIFTER Logic CPU CLK RESET*	75 76 112 76 59 41 82 102 48 109 (A89) 72 21	9 3 13 13 9 2 10 12 5,9 13	" 88-2 88-1 88-3 " 88-1 " 88-3 88-2 88-4 90-1 88-1 "	D3 D8 D7 A6 C5 B6 B6 B6 D7 C5 A8 A7 B8

SIGNAL LIST Table 1 - Nova 1210/1220

0	RIGIN			DESTINATION					
SIGNAL	СНІ₽	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
WRITE MEM	41	6	103-1	D2	X DRIVERS Y DRIVERS	72 76 73 77 79 74 78 75 54 62 52 66 60 50	3332222333322	103-3 " " " " " 103-4 " " " " " " " " " " " " " " " " " " "	A7 A7 A7 A7 A7 A7 A7 A7 A7 A7 A7 A7 A7 A
XRS XWS			103-3 103-3	B2 B2	X DRIVERS " " X DRIVERS " "	72 76 73 77 75 78 74 79	11 11 11 11 11 11 11 11	103-3 ''' '' '' ''	B7 B7 B7 B3 B3 B3 B3 B3 B3
YRS YWS			103-4 103-4	B2 B2	Y DRIVERS " Y DRIVERS " "	54 62 52 66 47 57 50 60	11 11 11 11 11 11 11 11	103-4 '' '' '' ''	B7 B7 B7 B3 B3 B3

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Intentionally
## ABBREVIATIONS

## CENTRAL PROCESSOR AND MEMORY

## NOVA 1210/1220

	**************************************	r	
ABC0 thru ACB15	Accumulator Buffer Register Outputs	DATIA	Data In A (I/O instruc- tion)
ACD	0 thru 15 Destination Accumulator	DATIB	Data In B (I/O instruc- tion)
ACD OUT	Destination Accumulator Out	DATIC	Data In C (I/O instruc- tion)
ACDP	Accumulator Deposit	DATOA	Data Out A (I/O in-
ACD 3 SEL	Destination Accumu- lator Select enable line	DATOB	Data Out B (I/O in-
ACD 4 SEL	Destination Accumu- lator Select enable line	DATOC	struction) Data Out C (I/O in-
AC EX	Accumulator Examine		struction)
ACS	Source Accumulator	DATA0 thru DATA15	I/O Data bus signals,
ACS 1 SEL	Source Accumulator Select enable line	D BUFFER	Destination (Accumulator) Buffer
ACS 2 SEL	Source Accumulator	INTA	Interrupt Acknowledge
ACTG0, ACTG1	Accumulator Timing Generator outputs 0 & 1	INTP IN	Interrupt Priority In (to Device)
ALC	Arithmetic Logic Class	INTP OUT	Interrupt Priority Out (from Device)
AND ENAB	AND (instruction) Enable	INTR	Interrupt (Bus Signal from Device)
CLK	Clock	IO $(F+D)$	IO (instruction) (Fetch or Defer state)
CLR	Clear	IO or I/O	Input/Output
CLR ION	Clear Interrupt On	ION	Interrupt On
CON DATA	Console Data	IO PLS	Input/Output Pulse
CON INST	Console Instruction	IORST	Input/Output Reset
CON RQ	Console Request	IO SKIP	Input/Output Skip
CONT	Continue switch at Console	IDO three ID7	(instruction)
CPU	Central Processor Unit		outputs 0 thru 7
CPU CLK	Central Processor Unit Clock	ISTP	Instruction Step (Con- sole switch)
CPU INST	Central Processor Unit Instruction	ISZ	Increment and Skip if Zero(instruction)
CRY ENAB	Carry Enable	JMP	Jump (instruction)
CRY OUT	Carry Out	JSR	Jump to Subroutine
CRY SET	Carry Set		(instruction)

## **ABBREVIATIONS** (Continued)

КЕҮМ	Key Memory (access	STRB A	Strobe A (Memory Stack)
	Load Accumulator	STRB B	Strobe B (Memory Stack)
LOAD ACP	Load Accumulator Buf	STRB C	Strobe C (Memory Stack)
LOAD ACB	fer (Shifter)	STRB D	Strobe D (Memory Stack)
LOAD IR	Load Instruction Regis- ter	STRT	Start (Console switch)
		SWP	Swap (bytes)
LOAD MBO	Load Memory Bus Out- puts (CPU Interface Register)	TS0 thru TS3	Time State 0 thru 3
		TT	Teletype
LOAD PC	Load Program Counter	TTI	Teletype In (Teletype Keyboard/Reader Buf-
MA1 thru MA15	Memory Address Reg- ister outputs 1 thru 15	ТТО	fer)
MA LOAD	Load Memory Address Register		Teletype Out (Teletype Teleprinter/Punch (Buffer)
MB CLEAR	Memory Buffer Clear	XRS	X (plane) Read Source
MBC8 thru MBC15	Memory Buffer Com-	<b>V</b> 31/0	(Memory Stack)
MRIOAD	Logd Momony Buffon	XW2	(Memory Stack)
MB LOAD	Register	YRS	Y (plane) Read Source (Memory Stack)
MBO0 thru MBO15	Memory Bus Outputs (CPU Interface Regis- ter) 0 thru 15	YWS	Y (plane) Write Source (Memory Stack)
MD SEL1	Multiply Divide Select 1	32 VNR	+ 32 Volts, Not
MD1-MD15	Memory Data 1 thru 15		Regulated
SET ION	Set Interrupt On	+ VINH	+ (Memory) Inhibit Voltage
SHIFT ACB	Shift Accumulator Buf- fer	+ V <sub>Lamp</sub>	+ Lamp Voltage (Con- sole indicators)
SHL	Shift Left	+ VMEM	+ Voltage Memory
SHR	Shift Right	+ 5 OK	+ 5 Volt (power)
SKIP INC	Skip Increment		operating properly
SL0 thru SL15	Sense Lines (Memory Stack) 0 thru 15		
S MULT	Source Multiplexer		
SNS0 thru SNS15	Sense Amplifier Out- puts 0 thru 15		
S0 thru S2	(Adder function) Select Control Bits 0 thru 2		
STOP INH	(Processor) STOP INHIBIT		

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